programmable timer/controller

basic microcomputer

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What is a TUN?
What is 10 n?
What is the EPS service?
What is the TO service?
What is a missing link?

Semiconductor types
Very often a large number of equivalent semiconductors exist
with different type numbers. For this reason, 'abbreviated' type
numbers are in use in Elektor wherever possible:
• '741' stands for μA741, LM741, MC1741, RM741, SN72741, etc.
• 'TUP' or 'TUN' (Translator, Universal, PNP or NPN respect-

ive) stands for any low fre-
quency silicon transistor that meets the following specifications:

UCO, max 20V
IC, max 100 mA
hfe, min 100
Plot, max 100 mW
fT, min 10 MHz

Some 'TUN's are: BC107, BC108

and BC109 families; 2N3652A,
2N3652B, 2N3653, 2N3654,
2N3947, 2N4124. Some 'TUP's

are: BC177 and BC178 families;
BC179 family with the possible
exception of BC169 and BC179;
2N4212, 3N2362, 2N3900,
2N4126, 2N4291.

Some 'DUS' are: BA127, BA217,
BA218, BA222, BA219, BA213.

Some 'DUG's are: OA85, OA81,
OA85, AA116.

BC107, 8 (9) families:
BC107, 8 (9), BC147, 8 (9),
BC117, 8 (9), BC227, 8 (9),
BC317, 8 (9), BC347, 8 (9),
BC547, 8 (9), BC671, 2 (3),
BC182 (3, 4), BC382 (3, 4),
BC437 (3, 4), BC414.

BC177, 8 (9) families:
BC177, 8 (9), BC157, 8 (9),
BC167, 8 (9), BC227, 8 (9),
BC320 (1, 2), BC351 (1, 2),
BC557 (2, 3), BC6251 (2, 3),
BC212 (3, 4), BC512 (3, 4),
BC581 (2, 3), BC641.

Resistor and capacitor values
When giving component values,
decimal points and large numbers
of zeros are avoided wherever possible. The decimal point is
usually replaced by one of the following abbreviations:
• p (pico) = 10⁻¹²
• n (nano) = 10⁻⁹
• μ (micro) = 10⁻⁶
• m (milli) = 10⁻³
• k (kilo) = 10³
• M (mega) = 10⁶
• G (giga) = 10⁹

A few examples:
Resistance value: 2.7kΩ = 2700 Ω;
Capacitance value: 4.7pF = 4.7·10⁻⁹ F
0.000 000 000 004 7 F...
Capacitance value: 10⁻⁹ C; this is the
international way of writing
10 000 pF or 0.01 μF, since 1 n is
10⁻⁹ and 1 μF.

Resistors are ± 5% carbon types, unless otherwise specified.
The DC working voltage of resistors is 50 V, and the
DC working current of resistors is 10 A, unless otherwise specified.

Test voltages
The DC test voltages shown are measured with a 20 kΩ
voltage, unless otherwise specified.
U, not V
The international letter symbol
'U' for voltage is often used
instead of the ambiguous 'V'.
'V' is normally reserved for 'volts'.
For instance: UV = 10 V,
not V = 10 V.

Mains voltages
A mains (power line) voltages are listed in Elektor circuits.
It is assumed that our readers know where mains voltages are
usual. Our readers are not.
The BASIC microcomputer card contains three relatively independent sections: a fully buffered and self-contained CPU, a NIBL interpreter in ROM and a standard interface. Adding one 4 K RAM card converts it into a complete microcomputer.

(p. 5-34)

This month's cover illustrates the possible uses of the programmable timer/controller: control of lighting and (central) heating, domestic appliances such as washing machines and cookers, coffee percolator or early-morning tea, etc. In general: automatic switching of equipment at fixed, preset times.

contents

programmable timer/controller .................................. 5-08

The circuit described is a versatile timer/controller, capable of switching 4 separate outputs on or off at 4 pre-programmed times every day. The circuit is ideally suited for the control of domestic appliances such as cookers, central heating, intruder alarms (to be switched on at night) etc., or can be used as a straightforward 24 hour 'delay-snooze-alarm' clock.

switching mains-powered equipment .......................... 5-13

If mains powered equipment is to be switched on and off by electronic circuits like the timer/controller, something more is required: an (electronic) relay. Four examples of this type of reliable and silent electronic relay are described.

random tune doorbell (A. Haughton) ......................... 5-17

delay lines (2) .................................................... 5-18

Having dealt with reverberation and echo in a previous article (see Elektor April, 1979) we now take a look at how delay lines can be used to achieve a wide variety of interesting special effects such as double tracking, vibrato, phasing, chorus etc.

CAPITALS from the ASCII keyboard ........................... 5-24

When programming in BASIC, only capitals are required. This option can be selected by adding one switch on the ASCII keyboard.

interface for μPs .................................................. 5-25

The specifications for a serial interface between computer and terminal are given by the so-called RS232C and V 24 standards - among others. Only a few components are required for a "standard" interface. The circuit described in this article can be used in conjunction with both the Elektor SC/MP system and the popular KIM 1.

sweep generator (L. Köpen) ................................. 5-28

Determining the frequency response of an amplifier normally requires a series of carefully conducted test measurements, a large supply of graph paper, and plenty of patience. However, if one possesses an oscilloscope, there is a way of displaying frequency response curves upon its screen — provided one also has the instrument described here, namely a sweep generator.

simple sound effects .............................................. 5-32

Using only two CMOS ICs, a wide range of sounds can be produced — varying from an American police siren to the twittering of birds.

BASIC-microcomputer .......................................... 5-34

It seems safe to assume that the "BASIC microcomputer" is the cheapest home-construction computer ever described that can be programmed using a higher programming language. The BASIC computer consists of not more than two Euro-carded printed circuit boards!

NIBL-E (O. Hendrikson) ........................................ 5-43

A BASIC interpreter for the SC/MP has been available for some time. However, this can only be used in systems where page 8 is available for storing the interpreter program. In the Elektor SC/MP system, part of page 8 is used for the monitor program. Even so, an adapted version can be incorporated into the Elektor system — as described in this article.

musical doorbell (L. Wirtgen) ................................ 5-47

market ............................................................. 5-48

advertisers index .................................................. UK-22

Supplement: BASIC (part 3), an introduction to a simple computer language.

The desire to have a distinctive "sound" is not restricted to musicians. People are also getting tired of old-fashioned doorbells, and even gongs and chimes are by no means unique. In this issue, a random tune doorbell and a musical doorbell are described; next month we will extend the range with a fully programmable doorbell.

(p. 5-17 and p. 5-47)

'Cheep cheeper' was also considered as title for the simple sound effects generator. However, this name doesn't quite do justice to a unit that can produce so many recognisable and unrecognisable noises!

(p. 5-32)
Our remarkable sense of pitch

(Dr R. A. Henson*)

To hear or sing even the simplest of tunes we need a sense of pitch. Our ability to judge it consistently is remarkable, but investigating how we do it is far from simple. Although we have quite a lot of information about the way the ear responds to sounds at various frequencies, we know very little yet about the subsequent central processing by the nervous system and the brain.

The pitch of a sound means its position on a scale of frequencies. Pitch sense is involved in perceiving all complex sounds; for example, human speech has its set of pitches. In this article the way pitch relates to music is considered.

In general, the pitch of a tone depends on its fundamental frequency, which determines whether it stands high or low on the musical scale. We tell one tone from another by their different fundamentals. Music is made up of a succession of tones and combinations of tones that are perceived, analysed and coded by the nervous system in ways to be explored, but questions of tuning and scales and how well we can hear them must be dealt with first.

Orchestral pitch is agreed nowadays as 440 Hz for A′, that is, the note A above middle C. It became necessary to agree this internationally because different pitches were used in different places and because a progressive heightening of pitch in the 19th century led to A′ as high as 461 Hz in some places. Musical scales are sets of pitches arranged in such a way that they contain a maximum of consonances, whereas various tones blend pleasingly, and a minimum of dissonances, where they do not. Tuning in ‘equal temperament’ has held the field in western music for three centuries because, unlike the earlier ‘perfect temperament’, it makes possible the use of all 24 keys (C major, C minor, C sharp and so on) without retuning. In equal temperament the octave is divided into 12 logarithmically equal steps of frequency, each to a frequency 5.9 per cent greater than the step below. The steps, called semitones, are each divided into 100 further equal steps or cents, and an octave covers 1200 cents. This method of tuning is imperfect and less accurate than the earlier forms. As Balbou, the eminent American composer and organist wrote, ‘all players and singers are playing false most of the time . . . these are errors of equal temperament.’

Have we an inbuilt tuning system?

Training and early exposure to musical stimuli make this question impossible to answer with assurance. However, we can say that the western musician’s internal pitch scale corresponds to equal temperament, but with a slight tendency to sharpen all notes relevant to the tonic or keynote; the target pitch for notation is a shade sharper than equal temperament.

Normal Capability

How much of the normal range of frequencies is actually heard depends on the age of the hearer and also on what is meant by ‘hearing’ a frequency. Some organs pipe is felt rather than heard. The figures commonly given are 16-20 000 Hz for young people and 20-16 000 Hz for adults. Hearing is most sensitive for frequencies between 1000 and 3000 Hz, being much reduced in the extreme lower and higher ranges. People’s ability to discriminate in pitch ranges from those who are tune-or tone-deaf to those with absolute pitch sense. Though it is highly developed in some, there is no experimental evidence that they can do better than discriminate between quarter tone intervals consistently. The ability to detect small changes of frequency diminishes sharply above 4000 Hz.

Some writers speak of tone ‘height’ and tone ‘chroma’. Tone height means pitch, whereas tone chroma indicates the colour or the way in which a tone affects a listener. It has been suggested that tone chroma plays a part in pitch identification, but Roederer** believed that there was no psycho-acoustic foundation for the notion, because all intervals are equal in the tempered scale; only the pitch is different. Maybe this is a metaphysical question, but there must be few musicians who would agree that C major sounds the same as E flat major. A sense of relative pitch is necessary for hearing or singing a simple tune. Most of us perceive and remember music in terms of changing sequences of pitch rather than in orchestral or other pitch values. Absolute or perfect pitch is the ability to name a sounded note or identify its frequency, or to do both this and to sing a given note accurately straight off. Possessors of absolute pitch appear to have an inbuilt pitch grid against which to measure incoming sounds, though there may be considerable lability or flexibility in the pitch reference points from day to day, for example, at the menstrual periods.

There has been a prolonged debate about whether absolute pitch is innate or acquired, but the present majority view is that both heredity and environment play their parts. Early training is needed for the development of absolute pitch, and important requirements probably include lengthy exposure to sounds of constant frequency and single, critical pitch experiences. Absolute pitch may be the normal manner in which we deal with frequency, but this is trained out of us by our musical environment, which depends on relative pitch. Certainly, absolute pitch can be learned in early childhood, but while pitch perception can be improved in adults by training, no one has been able to train adolescents and older people who had little original ability in pitch-naming. It is likely that high developed pitch-naming almost always derives from reinforcement of a child’s behaviour by an adult.

Perfect pitch is an advantage in some aspects of practical musicianship, but it also carries handicaps. For example, a singer has to transpose consciously when a key is changed. Interestingly, all

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* Neurological Department, the London Hospital.
** J. G. Roederer, Professor of Physics at the University of Denver, Colorado, USA.
normal people can retain information on absolute pitch for periods ranging from ten seconds to a few minutes, but the information is then discarded.

Pitch Perception
Musical notes must be sounded for at least two or three cycles before their frequencies can be precisely determined. The ear and the brain are more susceptible to the pitch changes of a melody than to blurred acoustic patterns, such as a glissando by a pianist. Problems of tuning and intonation must also be taken into account. Electronic analysis has shown that professional violinists and woodwind players deviate slightly from equal temperament in tuning or playing their instruments, and these deviations differ from one player to the next. In other words, they do not all play the same frequency for given notes. Fortunately, the auditory processing mechanism of the ear ignores minor fluctuations in pitch so that we place tones clearly in their right category. When fluctuations are larger the tone may seem out of tune, with the appearance of beats of one frequency against another, or be perceived as the next semitone or tone above or below the desired pitch. Considerations of this sort brought the suggestion that pitch may be defined operationally as the subjective correlate of each one of the auditory events contained in a musical performance.

The Peripheral Analyzer
The capacity of the human ear to analyze sound waves is truly remarkable. Perception of musical sound depends on several factors, including identification of the pitch, duration, intensity and rhythm of a series of tones, and this requires an efficient peripheral analyzer of the sound waves produced. Here we are concerned solely with the problem of pitch perception.

Many theories of pitch discrimination have been advanced over the past hundred years, but even now a united solution escapes us. Current knowledge and views tend to be pieced together as follows:

Sound waves are transmitted from outside via the ear-drum and the ossicles of the middle ear to the round window membrane, which sets up pressure changes in the cochlear fluids of the inner ear. The sound receptors of the cochlea are the inner hair cells, disposed along the basilar membrane. These cells are activated by a travelling wave which always passes throughout the membrane from the base to the apex of the cochlea. The travelling wave has its greatest amplitude at a point determined by the frequency of the sound stimulus. High frequencies cause vibrations in a small part of the base of the cochlear partition; low frequencies act the whole membrane into vibration. The place where the inner hair cells are activated may well account for the perception of high frequencies, and this idea is supported by the fact that people with disease at the base of the cochlea are deaf to high tones. But this theory does not explain how we perceive low tones, and it has been suggested that low frequencies are represented by the rate of nerve impulses engendered by the stimulus. The cochlear nerve fibres, which join the inner hair cells, cannot carry more than 500 to 600 impulses per second, and this led to a volley theory. This was that groups of fibres could carry frequency information, so that the stimulus frequency is represented in the combined pattern of nerve impulses produced. This idea is acceptable in a general sense, but there are objections to it on physiological grounds, especially where frequencies over 3000 Hz are concerned. Perhaps place and frequency patterns in time are the real stimuli of our pitch perception. Harmonics may help in identifying the fundamental of lower tones, for if a set of overtones is sounded, without the fundamental, the listener's ear supplies it and he hears it just the same.

Second Mechanism
This first stage of analysis by the basilar membrane is not enough to account for the fine degree of pitch discrimination achieved by the human ear. Studies on the mechanical tuning of the basilar membrane have shown it acts as a heavily damped, broadly tuned structure; on the other hand, recent recordings of the activity of a single auditory nerve fibre have shown that the tuning here is sufficiently fine to meet psychological requirements. There must be a second mechanism inside the cochlea to account for the difference in tuning between the two structures, and it has been suggested that the olivocochlear bundle, which runs from the brainstem to the inner ear, is involved in it. With higher intensities — for example, the orchestral fortissimo — the neural tuning of the cochlea is broad, and it seems that there must be a further tuning mechanism within the nervous system to deal with loud sounds. Single auditory nerve fibres have their own best frequencies, but they can also respond to neighbouring frequencies; that is to say, the frequencies that neurons respond to overlap. Looking at how the system works, an arrangement of this type would be essential to ensure the transition from one sound to another, whatever other sensory demands; it would also contribute towards the appreciation of loudness. Psychophysical studies suggest that frequency selectivity is achieved in man by the equivalent of a bank of overlapping filters, a system that would separate the individual components of a complex signal for analysis. Psychophysical measurements, known as critical bands, have been used to find the effective bandwidths of the human auditory system. It appears that these critical bands range from 200 Hz wide at 1 kHz to 2 kHz wide at 10 kHz. Such a mechanism could explain why we hear the normal differences in tuning or sounding of instruments; it does not allow a tone to be deviated from its pitch.

The auditory cortex of the brain. The final relay is in the thalamus, and from it auditory radiation flows to the auditory cortex. Apart from the complexity of the nuclei and linking tracts, investigations are made difficult because if anaesthetics are used; then evoked auditory responses in man and experimental animals are not normal, but, of course, more of these abnormal responses are obtained under anaesthesia than otherwise. In general, however, we can say that the organization of the cochlear response is maintained through the nuclei of the brainstem to the thalamus and auditory radiation. Experimental work on the cat
has shown that there is systematic cochlear representation in the primary auditory cortex, but opinions differ on whether the techniques used show the true state of affairs at this level.

The Auditory Cortex
The primary auditory cortex, that is the part of the brain solely concerned with input from the cochlear system, lies on an area surrounded by secondary cortex. In animals, this secondary cortex also appears to generate some systematic representation of pitch frequencies. The auditory cortex differs in some respects from other parts of the cortex, but the nerve cells are disposed in the usual columnar arrangement. Many of these cells are finely tuned and the number activated increases with sound intensity. The nerve cell population is not uniform, nor would we expect it to be because of the complicated input, carrying various information about sounds heard. Descending pathways from the cortex pass to those nuclei in the brainstem concerned with hearing. These pathways can be expected to shape and control pitch input by inhibiting and amplifying signals to ensure, among other things, that dominant frequencies prevail. There is evidence from observations on people with brain damage from strokes that humans can distinguish pure tones of different frequency without the intervention of the auditory cortex. But such patients cannot recognize complex sounds.

We do not know how the brain deals with auditory input. On general principles we may presume that incoming nervous impulses are analysed for such variables as pitch, duration, rhythm, intensity, sequence and location. This analysis is not confined to the cells in the immediate area of projection; neighbouring groups and columns of cells are also involved. After analysis comes synthesis. Within the cortex new pitch experiences, arriving as coded patterns of nerve impulses, are matched against the old, and the incoming stimuli are compared and contrasted with each other.

Further consideration of central pitch processing would involve discussion of psychological and psychophysical ideas which are beyond the scope of this article. However, we may conclude with the thought that many factors are involved in pitch discrimination, including semantic memory, musical memory, prediction and set and bias. Progress in our knowledge of the ways in which peripheral analysis of pitch takes place can be expected in the next few years. Solution of the problems of central pitch processing is likely to take much longer.

(Cassette Recorder with a brain)
Cassette decks used to be low-fi, easy-to-operate machines. You just popped in a cassette, hit the Record button and set the level. Over the years, however, they've been progressively upgraded; new types of tape have been introduced; noise reduction systems have been added. The result: cassette decks are now hi-fi — but they are anything but easy to operate. . . .

One of the main problems is the vast difference from tape to tape. Modern decks have an array of buttons that select the (hopefully) optimum bias setting and equalisation characteristics for various types of tape (Fe, CrO₂, FeCr, etc.). In practice, even this isn't enough to get the best out of the system, owing to the differences between even nominally identical tapes. A difference in sensitivity of one or two dB between, say, two CrO₂ tapes may not seem much — but if some kind of noise reduction system is used, any errors of this type will be aggravated.

So what do you do? Add more buttons? Or, worse still, add continuous controls? For most users, this would make matters worse instead of better — the chance of finding the 'correct' setting will decrease in proportion to the number of controls.

JVC have come up with a better solution: enlist the aid of our new friend, the microprocessor! In their new top-of-the-line cassette deck, the KD-A5E, top quality recordings can be made after an initial twenty-second alignment procedure that is carried out by the machine itself, fully automatically. After a cassette has been inserted, the so-called BEST system (for 'Bias, Equalisation, Sensitivity and Total') first selects the optimum bias setting for that particular tape. It then proceeds to select the correct equalisation and sensitivity settings for a flat 0 dB frequency response out to 10 kHz — worst case, that is, using standard tape!

What it does
Having loaded a cassette and operated the 'computer start' button, the sequence of (automatic) operations are as shown in figure 1. The first thing is to get past the tape leader and into the tape proper, so: 'Fast Forward Wind' for 1.5 seconds.

The machine now switches to Record. After erasing 2.5 seconds worth of tape to leave a gap, two 'index markers' are recorded: 60 ms pulses at -5 dB. A 1 kHz reference signal is then recorded at -15 dB, followed by a 6.3 kHz signal at the same level. During recording of this 6.3 kHz signal, the bias level is reduced in 32 steps — each step lasting 60 ms — from 30% above the 'average' bias level to 30% below. Now, the tape is rewound to the blank section and the test sequence is played back, the 'optimum' bias setting is the one that is found to give identical levels for the 1 kHz reference and the 6.3 kHz test signals.

During this bias setting procedure, the noise reduction circuits are by-passed and the frequency equalisation is set at an average level for that particular kind of tape. It is now time to 'fine-tune' this equalisation. A further test section is recorded, consisting of two index markers, the 1 kHz reference signal and
a set of 10 kHz test signals. As these 10 kHz sinewaves are recorded, first right channel only and then left channel only, the equalisation for the corresponding channel is increased in eight steps.

Finally, it is useful to set the recording sensitivity at the 'standard 0 dB' level — if only to make sure that noise reduction systems work properly! — and so the 1 kHz signal is recorded in sixteen level steps. The tape is now rewound and played back. The equalisation settings for both channels that give equal levels for the 1 kHz reference and 10 kHz test signals are selected; the 1 kHz test signals are compared with the original signal level to select the sensitivity setting that gives 0 dB overall gain.

Finally, the machine winds the tape back and signals that it's 'ready to go'.

**How it does it**

As stated earlier, the whole system works under microprocessor control. The 'program' is illustrated in the flow chart (Figure 2); most of it should be clear from the description given above. Starting at the top, the computer first wants to know whether or not its assistance is required. If the 'automatic flag' is not set, the bias, equalisation and sensitivity are simply set at 'nominal' levels, as in any normal cassette recorder. Assuming, however, that the flag is 'on' and the 'computer start' button is operated, the sequence of events described earlier is initiated: Fast Forward; RECord gap, markers, 1 kHz reference and 6.3 kHz test with varying bias; REWind and Play, Bias Select. At this point, a step is introduced that has not yet been mentioned: Error detection.

In the description given so far, we have blithly assumed that an 'optimum setting' for the various parameters will always be found. In practice, of course, this need not always be the case: the first section of tape may be damaged (causing severe drop-outs) or the tape characteristics may be outside the range of automatic adjustment. If this happens, the machine first checks whether this is its first try; if so, it repeats the whole procedure without first rewinding — so that the test signals are recorded on a new section of tape. If an error again occurs, it gives up and lights a flashing 'error indicator'.

Assuming that no error has occurred the bias is then correctly set — the next step is to record the equalisation and sensitivity test signals. The optimum settings are then selected; once again, if an error is detected the machine will have one further try.

If the setting-up procedure has been completed without problems, the machine will rewind the tape and indicate that calibration is complete.

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**Table 1**

<table>
<thead>
<tr>
<th>SPECIFICATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>(Normal tape)</strong></td>
</tr>
<tr>
<td>Frequency Response (Recording/Playback at -20 VU)</td>
</tr>
<tr>
<td>15 Hz - 17,000 Hz</td>
</tr>
<tr>
<td>(30 - 12,500 Hz ± 1 dB)</td>
</tr>
<tr>
<td>15 Hz - 18,000 Hz</td>
</tr>
<tr>
<td>(30 - 12,500 Hz ± 1 dB)</td>
</tr>
<tr>
<td>(at 0 VU: 25 - 8,000 Hz ± 3 dB)</td>
</tr>
<tr>
<td><strong>(SA/CrO₂ tape)</strong></td>
</tr>
<tr>
<td>Frequency Response (Recording/Playback at -20 VU)</td>
</tr>
<tr>
<td>15 Hz - 18,000 Hz</td>
</tr>
<tr>
<td>(30 - 12,500 Hz ± 1 dB)</td>
</tr>
<tr>
<td>(at 0 VU: 25 - 12,500 Hz ± 3 dB)</td>
</tr>
<tr>
<td><strong>(Metal tape)</strong></td>
</tr>
<tr>
<td>Frequency Response (Recording/Playback at -20 VU)</td>
</tr>
<tr>
<td>15 Hz - 18,000 Hz</td>
</tr>
<tr>
<td>(30 - 12,500 Hz ± 1 dB)</td>
</tr>
<tr>
<td>(at 0 VU: 25 - 12,500 Hz ± 3 dB)</td>
</tr>
<tr>
<td><strong>Signal to Noise Ratio</strong></td>
</tr>
<tr>
<td>58 dB [ANS - off]</td>
</tr>
<tr>
<td><strong>Wow &amp; Flutter</strong></td>
</tr>
<tr>
<td>0.035% (WRMS)</td>
</tr>
<tr>
<td>(DIN 45 500: 0.14%)</td>
</tr>
<tr>
<td><strong>Channel Separation</strong></td>
</tr>
<tr>
<td>35 dB</td>
</tr>
<tr>
<td><strong>Cross talk</strong></td>
</tr>
<tr>
<td>85 dB</td>
</tr>
<tr>
<td><strong>FF/REWind Time</strong></td>
</tr>
<tr>
<td>80 sec</td>
</tr>
<tr>
<td><strong>Total Harmonic Distortion</strong></td>
</tr>
<tr>
<td>1.2%</td>
</tr>
<tr>
<td><strong>Third harmonic Distortion</strong></td>
</tr>
<tr>
<td>0.5%</td>
</tr>
<tr>
<td>[0 VU, 1 kHz, UD Tape]</td>
</tr>
<tr>
<td><strong>Dimensions (W x H x D)</strong></td>
</tr>
<tr>
<td>450 x 120 x 396 mm</td>
</tr>
<tr>
<td><strong>Weight</strong></td>
</tr>
<tr>
<td>11 kg</td>
</tr>
</tbody>
</table>
Block diagram

In the same way that the flow chart gives a brief outline of the program, a block diagram will give some idea of the hardware involved (see figure 3). The switches and trimming potentiometers normally used are replaced by or supplemented with electronic circuits that are controlled by the microcomputer. Of the sections shown in the simplified block diagram, only a few require further explanation.

- ANRS or Dolby. This refers to the noise reduction circuit: ANRS is JVC's own version; Dolby is Dolby...
- Recording equalisation select and Bias select. These sections are controlled by a three-way switch on the front panel. The first position is correct for both normal and most high-performance tapes (CrO2, SA, XL-II, etc.); the second and third positions are for FeCr and metal tape, respectively. The corresponding equalisation characteristics are reasonably accurate for the various types of tape.
- Tape counter. Rapid and relatively precise 'tape position' information is obtained from a Hall device mounted on the mechanical tape counter: its output is fed to a counter in the microcomputer.

Results

The main specifications are given in table 1. It must be realised that these are 'guaranteed worst-case specs' - not just 'what you may achieve if you're lucky enough to use an ideally suited tape'...

A single test may serve to illustrate this. In figure 4a, the frequency response of a standard tape is shown - as obtained with the preset equalisations and sensitivity adjustments. As can be seen, the response in this case is 2 dB down at 3 kHz and 4 dB down at 15 kHz. Not bad. Figure 4b shows the response that can be obtained with the same tape - after the computer has done its job!

It might be argued that the same result could be obtained with more accurate preset adjustment. Not so. As shown in table 2, the recording sensitivity at 1 kHz can vary by as much as 2.6 dB for 'high quality' tapes, and this can have a distinctly noticeable effect on the frequency response if a noise reduction system such as Dolby or ANRS is used. Furthermore, the variation in frequency response for 12.5 kHz signals with respect to the 1 kHz level may vary by as much as 4.7 dB for nominally 'identical' tapes. Even if the effect of a noise reduction system is disregarded, it is impossible to guarantee a response within ± 1 dB if only preset adjustment is used!

The shape of things to come?

A fully decoded 256 x 4 bit non-volatile (1) random access memory has been announced by General Instrument Microelectronics Ltd. This RAM/FAROM, designated the FR1711, is intended for applications where data is constantly changing and must be protected in case of a power failure. The device operates normally as a RAM with a 1.5 micro-second cycle time. When powering down, a single negative pulse applied to the Erase/Write control line would disable the entire memory.
enters the entire contents of the 1024 bit memory into associated on-chip EAROM cells. All stored data is retained for 72 hours minimum after a 1 millisecond write pulse, or 30 days minimum after a 10 millisecond write pulse. Data can be recalled (restored into the RAM cells) by means of a power-up sequence followed by a bulk erase of the EAROM cells (a positive pulse on the Erase/Write control line).

The FR1711 is directly compatible with 4-bit microprocessors and typical applications include protection of process control state variables during power interruptions, machine and motor control to hold set points and feedback data, navigation equipment to hold constantly varying time and position data and cash registers for holding constantly changing cash totals. The FR1711 is available in both ceramic or plastic 22 pin dual-inline packages.

General Instrument Microelectronics Ltd,
Regency House, 1-4 Warwick Street,
London W1R 5WB, U.K.

15 kHz is enough for Golden Ears!

Everyone 'knows' that 20 kHz bandwidth is necessary for top-quality audio reproduction. Is it, though? For some time now, 'necessary bandwidth' has been the subject of heated discussions in the professional audio world.

The main reason for the sudden interest is the advent of digital audio. In digital systems, the audio signal must be 'sampled', and the sampling frequency determines the bandwidth. The sampling frequencies proposed vary between 32 kHz and 54 kHz — corresponding to theoretical audio bandwidths between 16 kHz and 27 kHz. At this point, the battle is joined . . .

Proponents of 32 kHz (broadcasting authorities, in particular) maintain that 'nobody heard the difference when we experimented with digital audio at a 32 kHz sampling rate'. 'No great trick', say the opponents, 'you've been using sharp 15 kHz low-pass filters for years'. Manufacturers of digital audio recorders introduce a new consideration: 'We can't sell digital recorders unless they can make it at least equal the specs of conventional analog equipment. A bandwidth of well over 20 kHz is therefore essential'.

At last year's AES convention in Hamburg, several groups announced that they were going to run tests to find the true bandwidth requirement for top-quality audio. This year, in Brussels, the results of some of these experiments were reported.

One typical test series can be briefly described as follows. A special test signal, containing harmonics at almost full level to well over 25 kHz, was reproduced via suitable loudspeakers (ionophones). A group of critical listeners (recording engineers and other 'Golden Ears') were used as Guinea pigs. Several low-pass filters were evaluated, with cut-off frequencies of 15 kHz, 18 kHz and 20 kHz, with filter orders varying from 7th to 15th order and with and without group delay correction.

Two loudspeakers were used; the signals could be the same (both filtered or both unfiltered) or one signal could be the original and the other after filtering. The test results were apparently somewhat surprising. Even with the 'worst possible' filter combination (15 kHz cut-off, 13th order, no group delay correction and two of these filters used in cascade), the percentage of 'correct' answers was only 62% for the most critical section of the test group. The percentage for the whole group was only 57%.

The conclusion drawn is that, even with a 15 kHz filter, differences will only be heard in extreme cases: signals with an extremely strong high-frequency content, a sufficiently broadband loudspeaker; listeners with exceptionally good hearing; and, finally, the possibility of direct signal comparison. An unlikely combination. It will be interesting to see the reaction in professional audio circles to these claims. Will it be ready acceptance ("OK, that's settled"), dogmatic refutation ("I don't believe it") or a call for further tests? It is interesting to note that at least three groups have already reached very similar conclusions: a representative of the broadcasting authorities, a record manufacturer and a manufacturer of digital audio tape recorders who has also introduced a digital audio disc system . . .

Based in part on AES preprint 1449, presented at the 62nd AES convention: 'What bandwidth is necessary for optimal sound transmission?'

G. H. Pfenge, H. Jakubowski and P. Schöne.

UK system will operate in 1980

Britain's Marconi space and defence systems company believes it has found the answer with a new automatic broadcast system which allows a computer to put together human speech. The system has been adopted by the UK Civil Aviation Authority and will be used to transmit in-flight weather reports from the summer of next year. Marconi says it has recorded the voice of one of its executives, Colonel John West, reading a range of standard weather report phrases, words and figures. These are converted into digital form and stored in a computer bank. When the computer is fed the latest telex report it automatically produces and arranges the sequence of words, phrases and figures needed to create a human voice report.

Marconi, which has more than 20 years' experience in voice digitization for military use, believes this technique will be adopted for much wider use. For example, practically all broadcast announcements at airports and mainline railway stations could be constantly updated and issued by automation.
The circuit described here is a versatile timer/controller, capable of switching 4 separate outputs on or off at 4 pre-programmed times every day. The circuit is ideally suited for the control of domestic appliances such as cookers, central heating, intruder alarms (to be switched on at night) etc., or can be used as a straightforward 24 hour ‘radio-snooze-alarm’ clock. Almost all the work is performed by a single IC, so that the circuit is both compact and relatively inexpensive.

The heart of the circuit is formed by the MM57160 standard timer and controller (STAC) chip from National Semiconductor. This IC is designed for use in timing applications where up to 4 separate outputs are required to operate at up to 4 user-programmed times. Thanks to direct display drive capability of the IC and on-chip keyboard scan facility, very little in the way of external hardware is required to provide a complete timer/controller system. The main features of the IC are summarised in table 1. An interesting facility is the provision of valid day programming, which allows control outputs to be inhibited on certain days (weekends, for instance).

Circuit design
The circuit diagram of the timer/controller is shown in figure 1. Timing is derived from the 50 Hz mains frequency at the secondary of the transformer and shaped by N1, N2 and N3. Mains transients are suppressed by the interference filter R1/C1. During the positive half cycle of the 50 Hz input signal C2 is rapidly discharged by N1. The capacitor takes much longer to charge up again, however, since this can only occur via R3, which is roughly 1000 times greater than R2.

The condition of each of the four outputs of the timer/controller chip (IC1) is indicated by a LED. Each output has a current capability of 20 mA but buffers are included to increase the maximum load current to 400 mA. It must be remembered that the use of the buffers inverts the output levels i.e. if the control output is low (0V) then the buffer output will be high (equal to + supply). This should be borne in mind when programming the system.

A stabilised power supply is provided, using a 78L08 regulator IC. Components R7 and C3 are included to ensure that the timer is reset upon power-on. Initial conditions are: (real time) clock to 00:00; all set point times to 00:00; and all outputs off; all days valid; and the IC in the real time clock mode.

<table>
<thead>
<tr>
<th>Table 1.</th>
</tr>
</thead>
<tbody>
<tr>
<td>24 hour real-time clock with 4-digit display</td>
</tr>
<tr>
<td>4 control outputs</td>
</tr>
<tr>
<td>4 programmable set point times with repeat every 24 hours</td>
</tr>
<tr>
<td>valid day programming to skip certain days of desired</td>
</tr>
<tr>
<td>manual mode to verify programming</td>
</tr>
<tr>
<td>each output can switch up to 400 mA</td>
</tr>
</tbody>
</table>

Programming
Programming is carried out using push button switches having up to three different functions and these are summarised in table 2. Set point times (switching times) are loaded as follows:
- The DATA ENTRY switch is momentarily depressed to take the system from the real time clock mode to the data entry mode, whereupon one of the set point times is displayed and its outputs status indicated on the decimal points of the display. If the data entry mode is selected immediately after power-up, the display will show 00:00, with the decimal points off.
- To examine the next set point, the ADVANCE SET POINT switch is depressed. The four set point values are stored in a revolving stack, so that four advances will cause the stack to roll round to the original value.
- Set point times are loaded or altered using the SET HOURS and SET MINUTES switches. When depressed, these switches increment the hour displays from 0-23 and the minutes displays from 0-59 at a rate of one per second.
- Next, the SET STATUS switch is used to program the output(s) to be activated at the set point times. When the SET STATUS switch is initially depressed the first decimal point is turned on, signifying that output 1 will be activated at this time.
- If this is the only output to be activated, the ADVANCE SET POINT switch can be depressed to go on to the next set point.
- If, however, output 2, 3 or 4 is to be activated, the SET STATUS switch should be pressed again to advance to the subsequent outputs. Each advance turns off the previous decimal point (and output).
- If more than one output is to be activated, e.g. 2 and 4, the HOLD STATUS switch is used to hold number 2 decimal point on before the SET STATUS switch advances through 3 to number 4. Thus using the SET STATUS and HOLD STATUS switches it is possible to program any combina-
Figure 1. Complete circuit diagram of the timer/controller. If desired, the output buffers N4 ... N7 may be omitted.
Table 2.

<table>
<thead>
<tr>
<th>KEY NO.</th>
<th>KEY SWITCH NAME</th>
<th>REAL-TIME CLOCK MODE</th>
<th>DATA ENTRY MODE</th>
<th>DAY MODE</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>MANUAL/REMOTE TRANS-</td>
<td>Remote transducer input; forces output 1 ON, outputs 2-4 OFF until next valid set point after switch is off</td>
<td>Manual verification mode; allows data to be transferred to outputs 1-4</td>
<td>(None)</td>
</tr>
<tr>
<td>2</td>
<td>HOLD STATUS/DEMO</td>
<td>Allows rapid demonstration of sequence by advancing clock at rate of 1 hr/sec</td>
<td>Holds output N ON while programming advances to output N + 1, N = 1-4</td>
<td>(None)</td>
</tr>
<tr>
<td>5</td>
<td>DATA ENTRY</td>
<td>Places unit in the data entry mode</td>
<td>RETURNS UNIT TO THE REAL-TIME CLOCK MODE</td>
<td>(None)</td>
</tr>
<tr>
<td>6</td>
<td>ADVANCE SET POINT/</td>
<td>Resets time of day to 00.00 without changing set points but resets all days to valid</td>
<td>Advances display to the next set point so that it may be verified or altered</td>
<td>(None)</td>
</tr>
<tr>
<td></td>
<td>RESET TIME</td>
<td></td>
<td></td>
<td>RETURNS UNIT TO THE REAL-TIME CLOCK MODE</td>
</tr>
<tr>
<td>7</td>
<td>DAY MODE</td>
<td>Places unit in the day mode</td>
<td>(None)</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>SET STATUS</td>
<td>(None)</td>
<td>Controls programming of outputs; resets output N to “0” (unless preceded by HOLD key) and advances to output N + 1</td>
<td>(None)</td>
</tr>
<tr>
<td>9</td>
<td>SET MINUTES</td>
<td>Advances minutes display of real-time clock</td>
<td>Advances minutes display of selected set point</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>SET HOURS/</td>
<td>Advances hours display of real-time clock</td>
<td>Advances hours display of selected set point</td>
<td></td>
</tr>
</tbody>
</table>

Figure 2
Rect time the SET HOURS and SET MINUTES switches are used. The clock time can be reset to zero by pressing the ADVANCE SET POINT switch in the real-time clock mode. The set point times remain unaffected by this operation, however it should be noted that it also resets the valid day information (i.e. all days are valid).

Finally, the MANUAL/REMOTE TRANSDUCER switch provides a facility for external inputs. When pressed in the real-time clock mode, the programmed data is ignored, and output 1 is switched on whilst outputs 2...4 are turned off. On valid days this condition is maintained until the next set point time. On non-valid days all outputs are turned off as soon as the switch is opened.

Construction

For ease of construction a printed circuit board (figures 2 and 3) is available from the Elektor print service. Since the display is made entirely of plastic it may be unwise to solder it directly to the board but it can be mounted in an IC socket.

The pin-out details for the display are given in figure 4 for those readers who may already possess a suitable type. It is often possible to pick up second-hand calculators and to extract the displays from them, thereby saving money. The only condition is that the display must be common cathode. If the pin-out of the display is unknown, it is possible to determine it by using a multimeter switched to a resistance range and checking each of the pins in turn to see which segment they light up. Use a discrete LED first to check that the meter is set to the right range.

Like the Beatles, some readers may have an application for an 8-day week cycle. This facility can be selected by wiring a switch in series with diode D1, or D4 can be mounted directly on the printed circuit board. Similarly diode D2, if removed from the board will enable the timer to be used with a 60 Hz mains frequency supply.

The choice of transformer, bridge rectifier and smoothing capacitor is determined by the maximum current consumption of the circuit, which in this case is 4 x 400 mA = 1.6 A. However, if the load current of each output is known to be less than the maximum, it is a simple matter to calculate the desired transformer current rating.

As a rule of thumb the value of the electrolytic can be calculated on the basis of 2000 µF per amp. The values shown in the circuit diagram for the power supply components are sufficient to drive several relays (12 V/20 to 50 mA). The relays, like the LEDs and their resistors, can be connected to the unregulated supply (positive end of C4).

One should check to ensure that the stabilised supply is satisfactory. With a voltage between 8 and 9.5 V trouble-free operation should be guaranteed. There is in fact no need for the supply voltage to exceed 8 V, and if one measures a voltage of more than 8.6 V, the diode D3 can safely be omitted. However if for some reason the voltage regulator provides less than 8 V, the diode must be included.

Upon switch-on the displays should show '0000'. If this is not the case then pin 11 of IC1 should be grounded providing an additional reset pulse, if the display still refuses to reset then there is a fault in the circuit (defective IC, bad solder joint, etc.).

It may at first sight appear that programming the timer is rather a complicated process. However with a little practice it is possible to enter and check (using the DEMO and MANUAL switches) a program extremely quickly. The following sample program should help to familiarise prospective users with program entry and operation.
To illustrate how the timer/controller can be programmed, assume that it is required to perform the following operations:

1. Output 1 should turn on at 14.00 and turn off at 16.00 each valid day.
2. Output 2 should turn off at 14.05 and turn on at 16.00 each valid day.
3. Output 3 should turn on at 14.00 and turn off at 14.05.
4. Output 4 should turn off at 15.01 and turn on again at 16.00.
5. Valid days are Monday to Friday inclusive. Saturday and Sunday are invalid days.
6. The current day is Monday, the time is 13.00.

From the above information we can construct the following 'truth table':

<table>
<thead>
<tr>
<th>Time</th>
<th>00 01 02 03 04</th>
</tr>
</thead>
<tbody>
<tr>
<td>14.00</td>
<td>1 1 1 1 1</td>
</tr>
<tr>
<td>14.05</td>
<td>1 0 0 1 1</td>
</tr>
<tr>
<td>15.01</td>
<td>1 0 0 0 0</td>
</tr>
<tr>
<td>16.00</td>
<td>0 1 0 1 1</td>
</tr>
</tbody>
</table>

The states of each output are illustrated in the timing diagram.

To load the above program into the chip memory the following sequence of key strokes is used:

**SWITCH**

**DEPRESSED**  
**DISPLAY**  
**REMARKS**

<table>
<thead>
<tr>
<th>DATA ENTRY</th>
<th>SET HOURS</th>
<th>SET STATUS</th>
<th>HOLO STATUS</th>
<th>HOLD STATUS</th>
<th>ADVANCE SET</th>
<th>POINT</th>
<th>SET HOURS</th>
<th>SET STATUS</th>
<th>HOLO STATUS</th>
<th>SET STATUS</th>
<th>DAY MODE</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>1400</td>
<td>1.400</td>
<td>1.400</td>
<td>1.400</td>
<td>1.400</td>
<td></td>
<td>1400</td>
<td>1.405</td>
<td>1.405</td>
<td>1.405</td>
<td>1.405</td>
</tr>
<tr>
<td>Initial display</td>
<td>Switch is depressed until first set point time is displayed.</td>
<td>Set point 1 at 14.00 (2 p.m.), output 1 ON</td>
<td>Hold output 1 ON</td>
<td>Hold output 2 ON</td>
<td>Output 3 ON</td>
<td>Hold output 3 ON</td>
<td>Output 4 ON</td>
<td>Set point 2 at 14.05 hours (2 05 p.m.), output 1 ON</td>
<td>Hold output 1 ON</td>
<td>Output 2 OFF, output 3 ON (second decimal point is extinguished, third decimal point turns on)</td>
<td></td>
</tr>
<tr>
<td>DATA ENTRY</td>
<td>SET HOURS</td>
<td>SET STATUS</td>
<td>HOLO STATUS</td>
<td>SET STATUS</td>
<td>ADVANCE SET</td>
<td>POINT</td>
<td>SET HOURS</td>
<td>SET STATUS</td>
<td>HOLO STATUS</td>
<td>SET STATUS</td>
<td>DAY MODE</td>
</tr>
<tr>
<td>0000</td>
<td>1400</td>
<td>1.400</td>
<td>1.405</td>
<td>1.405</td>
<td>1.405</td>
<td></td>
<td>1400</td>
<td>1.405</td>
<td>1.405</td>
<td>1.405</td>
<td>1.405</td>
</tr>
<tr>
<td>Initial display</td>
<td>Switch is depressed until correct set point time (minutes) is displayed.</td>
<td>Set point 2 at 14.05 hours (2 05 p.m.), output 1 ON</td>
<td>Hold output 1 ON</td>
<td>Output 2 ON</td>
<td>Output 2 OFF, output 3 ON (second decimal point is extinguished, third decimal point turns on)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

This timing diagram illustrates the changes in output status at the four set point times.

- **SET STATUS 1.501**: Set point 3 at 15.01 hours (3 01 p.m.), output 1 ON. No other output is required so the next step is simply to store this status information.
- **ADVANCE SET 0000**: The status information for the third set point is stored, switch is depressed until fourth set point time is displayed.
- **SET HOURS 1600**: Set point 4 at 16.00 hours (4 00 p.m.), output 1 ON.
- **SET STATUS 16.00**: Output 1 OFF, output 2 ON.
- **HOLD STATUS 16.00**: Hold output 2 ON.
- **SET STATUS 16.00**: Output 3 ON, Output 4 OFF, output 4 ON. Output 2 and 4 are now programmed to turn on at the next set point. All that remains to be at the first set point and status will be displayed.
- **DATA ENTRY 0000**: The timer is now programmed with valid day information. The first digit indicates the day, the second digit represents the status information.
- **DAY MODE 1 1**: The timer is now programmed with valid day information. The first digit indicates the day, the second digit represents the status information.
- **SET DAY 2 1**: Also valid day.
- **SET DAY 3 1**: Also valid day.
- **SET DAY 4 1**: Also valid day.
- **SET DAY 5 1**: Also valid day.
- **SET DAY 6 1**: A non-valid day, therefore...
- **SET STATUS 6 0**: This should also be a non-valid day, so...
- **SET STATUS 7 0**: Return to current day.
- **DAY MODE 0000**: Return to real-time clock mode.

The program can be checked by pressing the DEMO switch. As soon as this switch is depressed the clock will advance at a rate of 1 hour per second, lighting up the output LEDs in accordance with the program. Remember, however, that because of the buffers the LEDs will indicate the inverse of the real output status. Finally, the clock can be set to the correct current time using the SET HOURS switch.
Electronic relays

The programmable timer/controller, described elsewhere in this issue, is not really complete. It cannot be used to switch aquarium lighting and heating, for instance — not directly, that is. If mains powered equipment is to be switched on and off by electronic circuits like the timer/controller, something more is required: an (electronic) relay.

The programmable timer/controller will often be required to switch mains-powered equipment. One possibility would be to use the old and trusty mechanical relay, but this does have certain disadvantages. Being mechanical, the relay is relatively slow and prone to wear. Furthermore, it is rather bulky. For these reasons, it makes sense to use an up-to-date electronic replacement: the triac.

In industrial applications, the tendency is to use what is known as a 'solid state relay': a triac with associated electronics. Four examples of this type of reliable and silent electronic relay are described here.

The circuits are described in order of sophistication; each one can be used to replace mechanical relays, and even the simplest circuit is an improvement.

Optocoupling for safety.

There are two main reasons for using relays: a small control current can be used to switch a large load current, and the load is electrically isolated from the control circuit. This 'electrical isolation' refers to the fact that no current can flow from the load back to the control circuit. In other words, even if the load is connected to the mains it is still safe to touch the control circuit.

In a mechanical relay, isolation is given by the fact that the relay coil is not connected to the relay contacts. When it comes to the more up-to-date electronic version, this simple safety precaution is often omitted: the control circuit is connected direct to the triac and, with it, to the mains.

In most applications, it is advisable to restore the isolation between the two parts of the circuit. Some way must be found to transmit the control signal to the triac without any actual electrical connection. The obvious transmission medium, nowadays, is light. If the control circuit is arranged to light an LED and a photo-transistor is used to trigger the triac, electrical isolation can be maintained. When LED and photo-transistor are mounted in one package, the complete unit is known as an opto-coupler.

Synchronous or asynchronous?

Switching the mains voltage can be done in several ways. At this point, our main interest is the difference between synchronous and asynchronous switching. Synchronous switching refers to the fact that the load is turned on or off at the zero-crossing of the mains voltage (or current). This has the advantage that interference pulses are reduced to a minimum. However, everyone will have heard (or at least heard of) the horrible radio and TV interference that inferior lighting dimmers can cause!

Theoretically, synchronous switching has one drawback: the load is not switched on or off immediately. The circuit must 'wait' for a zero-crossing. However, since zero-crossings occur every 10 milliseconds, it is rare indeed for this to be a problem. Nobody is going to worry about an aquarium heater being turned off 10 ms late! The only reason why synchronous switching has not become standard practice is that the control circuit it requires is more expensive...

Circuit 1: simplicity itself.

A simple, reliable circuit for a solid state relay is given in figure 1. In this circuit, the load is not turned on at the zero-crossing of the mains, but it is switched off in synchronism. As in virtually all triac circuits, synchronous turn-off comes free: the triac turns off when the current through it drops below a certain minimum value, the so-called hold current.

The link to the timer/controller — or whatever other control circuit is used — consists of an opto-coupler. When sufficient current is passed through the LED, the photo-transistor will conduct. This, in turn, causes the 'darlington transistor' T1 to turn off, so that very little current can flow through the bridge circuit. (Note that two BC107s in cascade can be used instead of T1). In effect, the bridge circuit no longer forms a 'short' between points A and B, so that the voltage between these points can rise above the 'zener' voltage determined by DS and D6. Depending
During a triggered across opto-coupler 10 not that turn found this this the four dotted the the zero-crossing switched 'extinguish' sufficiently current thyristor thyristor photo-thyristor photo-resistor another ensures photo-'normal' mains triacs, connected is cause no is takes passed is the minimum mains the the the minimum.

---

The resistor R and capacitor C, connected across the triac, are especially important when switching inductive loads. The values depend on the type of load, as explained elsewhere ('RC network').

An improvement: synchronous switching

As explained above, it is usually better to switch the load at the zero-crossing of the current through the triac. In this way, interference 'spikes' can be reduced to a minimum. Turning off at the zero-crossing is no problem, as we have already seen; the triac takes care of this. Turning on is a different matter. Some way must be found to ensure that the triac is switched on when the voltage across it is zero - or 'as near as makes no muchness'. To put it another way: the triac must not be turned on halfway through a (mains) period, when the voltage is nowhere near zero. The circuit shown in figure 2 takes care of this. In this case, the link to the control circuit is an opto-coupler consisting of an LED and a photo-thyristor. The gate current for the triac flows through R1, the diode bridge and this photo-thyristor; the thyristor is turned on when it is illuminated by the LED - provided its gate is not shorted by T1. During most of the mains period, the voltage across the bridge circuit is sufficiently high to turn on T1; the voltage has to be less than about 20 V for T1 to turn off. Only at this point - close to the zero-crossing - can the photo-thyristor be triggered, turning on the triac. On the other hand, once the thyristor is triggered T1 cannot turn on, so that gate drive to the triac will not be interrupted.

When more than 10 mA is passed through the LED in the opto-coupler, the load will be switched on at the next zero-crossing. The connections to the programmable timer/controller are again shown in dotted lines; the values for the series connection of a resistor and a capacitor across the triac can be found from the separate explanation (see 'RC network').

Continuous drive for small loads

Both of the circuits described so far are reliable, provided the load is sufficient. One of the characteristics of triacs, however, is that they 'extinguish'
Figure 1. A straightforward electronic relay. The load is not switched on during the zero-crossing of the mains waveform – except by sheer chance.

Figure 2. An improved circuit that provides mains-synchronous switching.

Figure 3. A rather more complicated circuit is required for switching small loads. Gate current for the triac is maintained during the whole 'on' cycle.

Figure 4. A specially designed IC, the TDA 1024, can also be used. Broadly speaking, this circuit does the same as that shown in figure 2.

(cease to conduct) if the current passed through them falls below a certain value, known as the 'hold current'. This is not always a disadvantage: in the two circuits described above it is this characteristic that ensures that the load is turned off at the zero-crossing of the current. It does, however, become a drawback when the load is so small that the load current is less than the hold current. Fortunately, a triac will always conduct if its gate current is sufficient—regardless of whether the main current is sufficient to 'hold' it. For small loads, therefore, the gate current must be maintained for as long as the triac is to remain 'on'. This can be achieved as shown in figure 3, using two monostable multivibrators in a CMOS IC. The first monostable (MMV1) provides 1 ms pulses at the positive-going zero-crossings of the mains waveform; the necessary trigger pulses are derived from the mains by means of R2, R3 and R4. Note that two resistors in series are used, so that only half the mains voltage is dropped across each – ½ watt resistors cannot normally withstand more than about 250 V. For output pulses to be produced, the 'reset' input must be high; this is the case when the photo-transistor in the opto-coupler is conducting.

The output pulses from the first monostable are used to trigger MMV2. This second monostable provides 35 ms output pulses – equal to almost twice the period time of the mains waveform. These pulses are used to turn on the gate, providing gate current to the triac so that the load is switched on.

When no current flows through the LED in the opto-coupler, the photo-transistor will block, causing the reset input of MMV1 to go 'low'. No further pulses will be produced, so that at the end of the current 35 ms pulse the triac will cease to conduct, switching off the load.

The CMOS IC and transistor in this circuit require a low, positive supply voltage. When the load is to be switched on, gate current must be supplied continuously (approximately 100 mA). This effectively rules out the use of a series resistor and diode to derive the supply voltage from the mains: some 20 W would dissipate in the resistor! For this reason, a small transformer and bridge rectifier are used. The 'raw' supply (approximately 9 V) is used for T1; the supply to the CMOS IC and photo-transistor is stabilised with a zener diode.

The transformer secondary voltage is not particularly critical. If it is significantly more than 6 V, however, the values of R8 and R10 should be increased accordingly. Certain types of triacs may prove to require an exceptionally high gate current or be satisfied with an exceptionally low current, in which case the value of R8 can be modified. Nine times out of ten the value given should be correct.

It should be noted that both the primary and the secondary side of the power supply are connected to the mains! Under no circumstances should the same supply be used for another circuit — the control circuit, for instance. The complete circuit shown must be seen as an isolated unit: the only connections to the 'outside world' are the mains and load connections and the drive to the LED in the opto-coupler.

The connection to the programmable timer/controller has already been described; the RC series-connection across the triac is discussed elsewhere.
Finally: a special IC

A special integrated circuit for triac control is available from Philips: the TDA1024. It was used in the 'solid-state thermostat' described in last year's 'summer circuits' issue; a modified circuit for opto-coupler drive is given here (figure 4).

When the photo-transistor in the opto-coupler is illuminated, the IC starts to produce mains-synchronous pulses to trigger the triac. The width of the pulses is determined by R4, with the value given, a pulse width of approximately 150 μs is obtained. When switching small loads (a 40 W lamp, say) it is advisable to increase the value of R4 to the maximum permissible 820 kΩ so that the pulse width becomes 650 μs. The gate current is equal to 6 V divided by the value of R6; approximately 90 mA with the value shown. Since the trigger pulses are quite short, the supply to the IC can be derived from the mains via a dropper resistor and capacitor (R5 and C3). The advantage of using a capacitor is that the phase shift leads to a much lower power dissipation.

**Constructional notes**

The most important thing to watch in this type of circuit is the electrical safety. Every part of the circuit, with the exception only of the connections to the LED in the opto-coupler, is connected to the mains. Careful construction is therefore a must.

The choice of triac is determined mainly by the maximum load current. In some cases, switch-on surges can occur that are several times the nominal load current — particularly when switching motors, but to a lesser extent also if the load consists of incandescent lamps or heaters. The triac must obviously be rated accordingly. The same applies to the fuse; a 'slow-blo' type is preferable.

Adequate cooling is required for the triac. Note that the heatsink will also be connected to the mains, unless a mica insulating washer is used. Where resistor 'wattage ratings' or capacitor working voltages are specified, these should be adhered to — of course. Capacitor C should also have a working voltage of at least 400 V. In all other cases, ½ W resistors and 'normal' capacitors can be used.

The RC network

In each of the circuits, an RC network is connected across the triac. This network is intended to prevent the triac firing on at the wrong moment, or even being damaged. Two things must be prevented in any triac circuit: an excessively high voltage across the triac and an excessively rapid increase in this voltage.

Too high a voltage simply causes the triac to 'break down'. Triacs are commonly rated at 400 V, and 630 V types are also available. At first sight, 400 V seems an ample rating. However, when one considers that the peak voltage on a 245 V mains supply is approximately 346 V and that variations in the nominal supply voltage of ±10% are quite possible, the safety margin becomes alarmingly small.

The second point, an excessively rapid increase in the voltage across the triac, is perhaps less obvious. Most triacs can withstand a voltage increase at a rate of 200 volts per microsecond; a faster increase may cause the triac to turn on. One way to limit the rate of change would be to connect a 'fat' capacitor across the triac. However, if the triac is then triggered at a point where the capacitor is charged, the heavy surge current would almost certainly damage the triac. For this reason, a series resistor must be included. The minimum value can be calculated from the maximum voltage and current rating; for a 6 amp triac, for instance:

\[
R = \frac{V_{\text{max}}}{I_{\text{max}}} = \frac{346}{6} \approx 56 \Omega
\]

A further point to watch is the effect of an (even partly) inductive load. The RC network across the triac and the RL network formed by the load together represent a series RL circuit. If this resonant circuit is insufficiently damped (damping d < 1) oscillation can occur with the triac switching on and off at a frequency determined by the RL network. At the same time, the voltage can swing up to above the maximum rating of the triac. When selecting the resistance value, therefore, the damping in the resonant circuit must also be estimated. If all resistances are taken together as Rpot and the inductances are summed in the same way, the damping is given by:

\[
d = \frac{R_{\text{pot}}}{2 \sqrt{LC}}
\]

Since the whole idea is to damp out voltage spikes with a capacitor, it is logical to use a 'fat' one. In practice, 47 μF/1000 V...340 μF will normally be used. The series inductance of mains wiring and load can be estimated as 100 μH in most applications (barring truly inductive loads). If the load consists of, say, a 60 W lamp (with a resistance of 1 kΩ) and a 56 Ω resistor is used for R, the damping will be:

\[
d = \frac{1056}{2 \sqrt{\frac{100}{10^4} + 47 \times 10^{-9}}} \approx 11.7
\]

The rate of change must be checked with these new values:

\[
dV = \frac{10^4 \times 3.346 - 3.46 \text{ V/μs}}{1}
\]

Perfectly safe.

Summary

For 'normal' loads (incandescent lamps, heating elements etc.) up to 1 kW, a 6 A triac can be used. In this case, a safe value for R is 56 Ω/1 W and a good capacitor value is 47 μF/400 V. There is no harm in playing it safe: the capacitor value can be increased to 100 μF and the working voltage to 630 V if desired. For 10 A triacs (loads up to 1600 W), the resistance value can be decreased to 39 Ω, provided a 100 μF capacitor is used. The same values can be used for 15 A triacs; 22 Ω and 150 μF or 220 μF are also permissible in this case.

When switching fluorescent lamps (note that 'dimming' is impossible with these circuits!) the value of R will have to be increased considerably — to over 10 kΩ. If other 'odd' loads are to be switched, the corresponding values for R and C can be calculated as described above.
The circuit diagram of the ‘random tune’ doorbell is shown in figure 1. As can be seen, it basically consists of two squarewave generators, a counter, and a current controlled oscillator. The frequency of the first squarewave generator (N1/N2) can be varied between approx. 12 and 900 Hz, whilst that of the second generator (N3/N4) is roughly 1 kHz. The counter, IC3, is enabled when the clock enable input is taken low. However due to the integrating effect of C3/R4, the negative going edge of the first squarewave enables the counter for only a brief period. The count is only incremented when a positive going edge from N3/N4 coincides with a clock enable pulse, whereupon the counter is once more incremented. Thus each of the counter outputs is taken high in turn.

The outputs are commong via resistors R6 ... R13 and fed via P2 to the current controlled oscillator T1/T2. Thus the value of whichever output resistor is high, together with the setting of P2, determine the pitch of the oscillator signal. The result is a semi-random tune, in which the length of each note is dependent upon the length of time between clock-enable and clock pulses coinciding.

In order to introduce a pause between successive cycles of the counter, output 0 of the counter is left floating. Similarly, by leaving output 5 (pin 1) unconnected, each ‘phrase’ will consist of two groups of four notes, separated by a rest. Thus the ‘tune’ will always have a certain basic ‘shape’, regardless of variations in the length of successive notes.

In order to eliminate the possibility of the two squarewave generators influencing one another, i.e. tending to synchronise, it is advisable to use separate 4011’s for each.
delay lines (2)

Having dealt with reverberation and echo in a previous article (see Elektor 46, February 1979) we now take a look at how delay lines can be used to achieve a wide variety of interesting special effects such as double tracking, vibrato, phasing, chorus etc. Such applications are of particular interest to the amateur musician since they can be implemented using relatively short delay lines and hence at comparatively low cost. The article is rounded off with a look at the contribution of delay lines to studio recording techniques and sound reinforcement systems.

Unlike reverberation and echo, such effects as vibrato, phasing, flanging, chorus and string ensemble can be obtained using comparatively short delay lines. In practice, a single bucket-brigade memory is often all that is required. As we shall see, most of the effects mentioned above are achieved by varying the frequency at which the audio signal is clocked through the delay line, however there is one commonly used technique where this is not the case.

Automatic Double Tracking (ADT)
The block diagram of figure 1 illustrates the simplest application of a short delay line, in which the audio signal is delayed by approx. 1 to 5 ms and then summed with the direct signal. The result is that a solo voice or instrument is made to sound ‘fuller’ or stronger, since the human ear is unable to distinguish between the original and delayed signals and has the subjective impression of increased volume. The actual increase in signal amplitude, however, is considerably smaller than the perceived increase in volume (which can be anything up to 6 dB), thus there is no danger of equipment overload on signal peaks. If several double tracking elements are connected in cascade, a multiple voice effect is obtained, this being the first step towards ‘chorus’.

Chorus
True chorus effect is obtained when the delay time is not constant, but is subject to small variations. In the case of both digital delay lines and analogue ‘bucket-brigade’ memories the delay time is determined by the clock frequency and the length of the delay line. Thus the delay time can be varied by using a voltage controlled oscillator as clock generator, which is modulated by a low frequency random voltage generator (see figure 2a). In practice more than one delay line is used. The circuit shown in figure 2b consists of 4 delay lines, each of which is independently varied by a random clock signal. The principle of chorus generation is to simulate the effect of a multiplicity of sound sources — as are present in a voice or string section of an orchestra.

Although a group of instruments may be required to play the same note, due to variations in the phase relationship of each sound the human ear perceives that several instruments are present. These phase discrepancies are caused by slight differences in the mechanical construction of similar instruments, differences in the musicians’ technique and in the different path lengths which the sounds must travel to the listener or recording microphone. Thus randomly varying the length of the delay lines ensures that the phase relationship of the output signals is constantly changing, thereby producing a multiple image effect. For simulation of complex orchestral sounds, in particular those of stringed instruments, the arrangement of figure 2c is used. The modulation signals of the clock generators (VCOs) are periodic, not random, and are locked out-of-phase with one another. The result is that whilst the delay time of one line will be increasing, the delay time of another will be decreasing, and vice-versa. As the length of the delay lines are varied, so is the phase relationship of the signals at the output. A second ‘fast’ modulation signal superimposed on the clock frequencies has the effect of further enhancing the pattern of phase differences and produces a rich, heavily textured sound composed of an apparent multiplicity of separate instruments.

Vibrato and Phasing
If a periodic clock frequency signal is used instead of a random clock signal, vibrato and phasing can be obtained. Figure 3a shows a basic circuit for vibrato, whilst 3b illustrates how phasing can be achieved. As can be seen the basic difference in the two circuits is that the vibrato signal is taken directly from the output of the delay line, whilst in the case of phasing, the delayed and direct signals are summed. Vibrato essentially involves alternately speeding up and slowing down the sampled signal as it progresses through the delay line. Since the rate at which the signal enters the delay line is different from that at which it exists, the result is variations in the pitch of the
**Figure 1. Basic principle of ADT — automatic double tracking.** A very slightly delayed version of the audio signal is summed with the original. The result is that the signal is intensified, without a significant increase in signal amplitude. Figure 1b shows a practical circuit for such an arrangement.

**Figure 2a. Block diagram of a basic chorus generator.** By randomly varying the clock frequency of the delay line, the changing phase relationships between the direct and delayed signals produces the effect of a multiple sound source similar to that of a voice choir.

**Figure 2b.** In practice more than one delay line is normally used. In the circuit shown here, there are four delay lines, the clock frequencies \(f_c_1 \ldots f_c_4\) of which are independently varied by separate random voltages.

**Figure 2c.** For string ensemble effects a multiple phasing unit of the type shown here is used. The principle involved is similar to that of the circuit in figure 2b, however in contrast to the above circuit the clock frequencies of the delay lines are modulated by periodic (not random) signals. In fact two modulators are used, one 'fast' and one 'slow', and the modulation signals to each VCO are held in a fixed out-of-phase relationship. When the outputs of the delay lines are summed, the periodic variations in the delay time of each line lead to highly complex phase patterns which lend the resultant sound a rich, vibrant quality characteristic of a string section.
signal, i.e. frequency modulation. Relatively short delay times are used (approx. 5 ms), which means that high clock frequencies are possible and hence input signals with a wide bandwidth can be processed in this way.

The modulation rate is normally in the region 5 to 10 Hz. The modulation depth (i.e. the extent to which the signal frequency is shifted up or down) of the vibrato signal is determined by the average delay time of the delay line, the modulation depth of the clock signal and the rate of modulation (vibrato frequency). Thus with a delay time of e.g. 5 ms, a variation in clock frequency of ± 5% about an average value, and a vibrato frequency of 10 Hz, the signal frequency will vary by ±3.14%. As a comparison, the musical interval of one semitone corresponds to a frequency change of just under 6%.

Phasing is an effect which is extremely popular with many musicians, and one which is very difficult to describe! Many people liken it to the effect of passing the sound through a long tunnel, or describe it as a 'wooshing' effect, the music seeming to 'breathe' in and out in a regular rhythm. This highly individual sound is obtained by summing the direct and delayed signals. At frequencies where the delay is equal to an odd number of half periods of the signal frequency the direct and delayed signals will be 180° out of phase and therefore cancel. Conversely, at frequencies where the delay time is equal to an even number of half periods, the two signals will be in phase and reinforce. The result is a series of attenuation notches in the response of the signal at the odd harmonics of the fundamental. The process is the equivalent of passing the audio signal through a comb filter. The distance between successive notches is inversely proportional to the delay time, and is in fact equal to \( \frac{1}{T} \), where \( T \) is the delay time. Thus with \( T = 10 \) ms, the frequency response of the output signal will exhibit a notch every 100 Hz. By cyclically varying the delay time (by low frequency modulating the clock oscillator) the distance between successive peaks in the response is also varied (see figure 4), and it is this which produces the characteristic phasing effect. Delay times for phasing are normally between approx. 1 and 20 ms, whilst the modulation signal from the low frequency oscillator is generally a sine wave or triangle, with a frequency between roughly 0.05 Hz (i.e. one complete cycle every 20 seconds) and 1 Hz.

**Frequency Modulator for Chorus, Phasing and Vibrato**

Figures 5a and 5b show the block diagram and circuit diagram respectively of a frequency modulator using the TDA 1022 bucket-brigade memory. This circuit forms the basis of an audio effects unit for chorus, phasing and vibrato. A simple VCO built around two BC 337 (or BC 107) transistors provides the clock signal, whose frequency can be modulated by means of a separate sinewave oscillator. The frequency of this vibrato oscillator can be varied between 0.5 and 7 Hz by means of a 100 k potentiometer. The modulation signal is fed to the VCO via an emitter follower, whose emitter resistor is formed by a potentiometer (intensity) thus allowing the modulation depth to be varied.

A random voltage circuit is included in order to provide aperiodic phasing/vibrato (chorus effects). The random voltage is derived by simplifying and low pass filtering the noise voltage of a 13 V zener diode (more commonly available 12 or 13 V, 0.4 W zeners can also be used). When switched into circuit, the random voltage controls the vibrato oscillator, which in turn controls the VCO. The intensity of the random voltage modulation can also be varied by means of a potentiometer (random intensity).

Figure 5c shows the circuit of a suitable lowpass input filter to limit the bandwidth of the audio input signal. As was explained in the first part of the article, since the clock frequency must be at least twice
the maximum signal frequency, there is a trade-off between delay time (which of course is determined by clock frequency) and signal bandwidth. The filter shown here has a turnover frequency of 15 kHz and a filter slope of 24 dB per octave.

The circuit of an audio effects unit for phasing, vibrato and chorus using the above frequency modulator is shown in figure 5d. Potentiometers P1 and P2 determine the relative proportions of direct and delayed signal mixed at the output. If the delayed signal only is fed to the output, vibrato is obtained. As a rule fairly fast vibrato, i.e. a modulation frequency of several Hertz, is best, whilst the modulation depth (clock frequency deviation) should be kept low. If the direct and delayed signals are mixed, either chorus or phasing is the result, depending on whether a random or periodic modulation signal is used. A gradual transition from vibrato to phasing can be obtained by slowly increasing the amount of direct signal summed with the delayed version. The above circuit can also be used for ADT. With the vibrato intensity turned right down, a constant delay time of approx. 3.2 ms is obtained. Mixing direct and delayed signal will then produce the double tracking effect.

**Stereo phasing**

For multi-channel effects, the add-on
circuit of figure 6 provides three separate output signals. Output I gives the sum of the delayed and direct signals, at output II is the direct signal minus the delayed signal, whilst at output III is the delayed signal minus the direct signal. Stereo phasing, chorus and ADT are obtained by taking either outputs I and II or I and III as the stereo signal pair. In case of vibrato, obviously all three outputs will give the vibrato signal, with output II being inverted with respect to outputs I and III. Any of the three outputs can in principle be used to provide a mono signal, however it is normal to use the sum signal at output I.

Sound reinforcement systems and studio work

With the aid of delay lines it is possible to exploit two interesting psycho-acoustic phenomena related to the time taken for sound waves to travel through free air.

The Haas effect and the law of the first wavefront

According to the theory of Dr Haas, a blindfold listener will determine the source of a sound not by amplitude, but on a 'first arrival basis'. If for example the same signal is fed to two loudspeakers of a stereo system, delaying the signal to the left channel speaker by several milliseconds will give the listener the impression that the music is originating almost entirely from the right channel speaker. Even if the volume of the left channel signal is increased to several times that of the right channel, the listener will continue to be deluded into thinking the sound is coming exclusively from the right-hand speaker. The increase in left channel volume only affects the listener's impression of overall loudness of the signal; it has little or no effect on the perceived direction.

The use of electronic delay lines allows the sound technician to focus the listener's attention on a particular sound source by ensuring that the other signals are delayed. When recording orchestral music delay lines are often used to counteract the effect of different path lengths between individual instruments and the microphones. Thus when recording a large orchestra using one main stereo microphone (for good transparency and resolution) supported by a series of secondary microphones to pick up instruments further removed from the main microphone (e.g. second violins), the latter tends to pick up the sound of distant instruments after the more closely positioned microphone. Due to the Haas effect this can lead to falsification of the desired stereo image, a problem which is only partially resolved by lowering the level of the secondary microphone. The ideal solution is to employ delay lines to equalise the path lengths.

A similar technique can be used when recording an orchestra with a main microphone close to the body of the orchestra and one or more secondary microphones positioned further back in the hall to capture reverberation. At distances of greater than 15 m between main and secondary microphones, the time taken for signals to reach the two can differ by more than 50 ms. Path length differences of this order can produce intrusive echoes. By employing delay lines the main microphone signal can be held back to reduce the period between direct and reverberation signals to acceptable levels.

In the case of P. A. systems used in large halls or in the open air, excessive path
length differences between signals from different loudspeakers can also cause the intelligibility of the speech signal to be impaired. Here again delay lines can be used with advantage to reduce the intervals between direct and reverberation signals reaching the listener to below the crucial 50 ms mark. The ideal interval between successive signals is in the region of 20 ms, since the effect is then similar to that of double tracking, i.e. the listener 'integrates' the two sounds and subjectively experiences a slight increase in the volume of the signal.

In the case of loudspeaker installations which do not incorporate delay lines, the first signal to reach the listener will be that from the loudspeaker closest to him, which normally will not be situated in the line of sight between himself and the person speaking into the microphone. Thus, due to the first wavefront principle, he will see the speaker in front of him, but will hear him from the side, a phenomenon which can often have a slightly disconcerting effect.

The problem can be overcome by using a small loudspeaker at the front of the stage or hall to reproduce the direct signal, and delaying the signal to the remainder of the loudspeakers sufficiently to ensure that their signals reach the audience after the signal from the front loudspeaker. If a suitable delay time is used the output of the front loudspeaker can be considerably smaller than that of the others. Once again, with a delay of approx. 20 ms between successive signals the listener perceives them as simultaneous and the intelligibility of the speech signal is improved.

**Variable Speech Control, Level Control and Anti-Click Units**

Variable speech control is a process which allows recorded speech to be replayed at faster or slower speeds, without affecting the pitch of the signal. As every owner of a variable speed tape recorder knows, playing back a recording at a higher than normal speed produces a high-pitched twittering sound, whilst lower speeds give an incomprehensible deep grumbling noise. Variable speech control prevents these changes in voice pitch. Signal I in figure 7a shows 9 cycles of a 200 Hz sinewave recorded at normal speed. When played at twice the recording speed the signal frequency is doubled to 400 Hz (signal II). Variable speech control 'stretches' the first four cycles of signal II to twice their 'length' i.e. the time domain of the signal is compressed. The result is signal III, which has the original frequency of 200 Hz. Cycles 5...8 of signal II (shown dotted) are suppressed. The informational content of these 4 cycles is in fact superfluous, with means that the intelligibility of a speech signal is unaffected by replay at twice the original speed.

When replaying at half the original speed the opposite occurs. The original
signal is slowed down to a frequency of 100 Hz (signal IV). The section of signal containing the first four cycles is compressed into half its original period (signal V), the resulting 'hole' or time gap is filled by repeating the first four cycles, which have been specially stored for this purpose (signal VI). Since the pitch and speech rhythms (at half their normal speed) of the original signal are preserved, the extra information is not important.

In practice the pitch signal is processed by feeding it through a bucket brigade memory and continuously varying the clock frequency. A simplified block diagram of a variable speech processor is shown in figure 7b. A sawtooth generator, the frequency of which is determined by the speed of the tape recorder, is used to modulate the clock generator of the delay line. In the case of faster than normal playback the sawtooth ramps negative. During each period of the sawtooth the clock frequency is continuously varied from a maximum to a minimum value. The lower the clock frequency, the longer each successive sample takes to travel through the delay line. The result is that the time domain of the output signal is extended (its frequency is reduced), whilst leaving the shape of the waveform unaffected. Since all the frequency components of the original signal were 'slowed' by the same relative proportion, the harmonic structure and therefore the tonal character of the signal are preserved.

In the case of speech expansion (the time domain of the speech signal is expanded by playback at a slower than normal speed) the opposite occurs. The sawtooth ramps positive and the clock frequency varies from an initial minimum to a maximum value, with the result that the pitch of the signal is increased.

The variable speech processor can also be used to falsify the pitch of signals played at their correct speed, i.e. real-time pitch shifting. Thus by expanding the time domain of the speech signal the effect is of increasing its frequency and pitch, a trick which can be used for cartoon voices etc. Conversely, by compressing the time domain of the speech signal its frequency can be lowered. This technique is useful in unscrambling the voice signals of divers working in helium-filled atmospheres.

Finally, two closely-related applications of delay lines in specialised studio equipment: level control units and click eliminators. In both cases the principle involved is the same, an audio signal is monitored for a particular irregularity.

In one case it is signals above a preset maximum level, and in the other case a particular type of noise or distortion (clicks or pops caused by scratches, old recordings etc.). Delay lines are used to give the control circuits sufficient time to respond to signal overloads or noise transients. The basic arrangement is illustrated by the block diagram of figure 8. The input signal is fed to a delay line and to a detector circuit which controls the limiter or noise suppression circuit. Since the signal fed to the detector circuit is undelayed in the case of e.g. a signal overload, gain reduction sufficient to prevent overshoot will have occurred before the delayed signal (and signal peak) arrives at the limiter. Due to the reduction in the cost of bucket brigade memories, click suppressors are now a feasible proposition for the amateur, who can make more or less noise-free recordings of old records which previously were 'unlistenable-to'.

Figure 8. Basic principle of a level control circuit incorporating a delay line. The detector monitors the input signal for overloads, and as soon as a signal peak is detected, activates the limiter circuit. The delay line ensures that the gain reduction occurs before the input signal reaches the limiter, thereby preventing initial transient distortion. The same principle can be used for click suppressors etc.

The ASCII keyboard (Elektor, November 1978) is more versatile than may appear at first sight. Some readers have commented that a 'shift-lock' would be useful, particularly when it is used for programming in BASIC. In actual fact, we can go one stage further: an 'upper-case lock'!

In the ASCII code, capitals and lowercase letters are distinguished by the value of the sixth bit (S6 on the character generator). For capitals, this bit is logic '1', for lowercase letters it is logic '0' (see table 1 in the original article). The character generator used, the AY-5-1866, not only provides the usual 7-bit ASCII code: it has an eighth output (S8). Although this is not made clear in the data sheet, S8 can be used instead of S6. The result is all that could be desired: the shift key operates normally for numerals, punctuation marks etc. - but only CAPITALS are printed when a letter key is operated!

This facility can be extremely useful - for instance, when programming in BASIC. The 'shift' key need only be used when special symbols are required; it is no longer required for printing text. A single-pole change-over switch can be added as shown in the figure.

![Diagram of ASCII keyboard and level control circuit](image-url)
The specifications for a serial interface between computer and terminal are given by the so-called RS232C and V 24 standards—among others. Although these standards are in widespread use, this is not to say that all (micro-)computers include the corresponding interface. Only a few components are required for a 'standard' interface. The circuit described in this article can be used in conjunction with both the Elektor SC/MP system and the popular KIM 1.

The main difference between computer- and RS 232C/V24 signals is the definition of the signal levels. Within a computer system it is common practice to use TTL levels, with logic '0' corresponding to 0 V and logic '1' to +5 V. The interface standards are rather different: logic '0' may be anything between +5 V and +25 V, and logic '1' is 'defined' as between −5 V and −25 V. Note the level inversion: positive voltages for logic '0' and negative voltages for logic '1'! The supply voltages in the SC/MP system are ±5 V and ±12 V, so it is 'logical' to use these levels for '0' and '1' respectively.

No negative supply voltage is available in the KIM 1 system, so an additional power supply must be added (giving a voltage between −5 V and −25 V). Two positive voltages are present (+5 V and +12 V). Either of these could be used for the positive logic level, but the higher voltage is to be preferred since it gives better noise immunity. The only disadvantage is that the power dissipation is higher in this case.

**SC/MP interface**

The input/output software for the SC/MP normally uses the sense B input and flag B output for serial data transfer. A suitable interface for these connections is shown in figure 1. The input interface (figure 1a) consists

**Figure 1. Interface for the SC/MP system.** The input side is given in figure 1a, and the output in figure 1b.
of four components. A diode (D1) and resistor (R2) limit the input signal, after which the transistor performs the conversion to TTL levels. Resistor R3 is not required if the input signal conforms to the official standards. However, the interface can also be fed from an optocoupler or open-collector gate; in either of these cases R3 can be used as pull-up resistor.

The output side of the interface is slightly more complicated. The TTL levels from the SC/MP must be converted to +5 V and -12 V. A low output impedance is a must, since lines of up to 10 m (30') are quite common. Furthermore, the circuit must be short-circuit proof.

Figure 2b gives the circuit. A current source (T3) is used to obtain the low output impedance; it has the added virtue of being short-circuit proof. A second transistor (T2) is included as an inverter, to obtain the correct logic level relationship between the flag output and the interface output. Resistor R5 is not strictly necessary; it improves the switching characteristic of the interface, giving sharper edges. The second output, via diode D4, can be used to drive the LED in an optocoupler. The output current will have to be reduced in that application, by increasing the value of R7 to 15 Ω.

The same circuit can also be used for buffering the flag output, without altering the levels. In that case R8 should be connected to supply common instead of negative supply. The printed circuit board (figure 3) is designed to cater for all possible applications.

KIM interface

Only a few modifications are required if the interface is to be used in conjunction with the KIM 1. The TTY (teletype) interface in the KIM system will also have to be modified slightly.

The serial data input is no problem: the same circuit can be used. The only difference is that the value of R1 in figure 1a must be reduced to 470 Ω to cope with the heavier load requirement. The circuit is therefore as shown in figure 2a; it can be connected to the KIM's 'application connector' as shown.

For the serial output, some minor surgery on the KIM board is required. The TTY output on the KIM is intended for teletypes with a so-called current loop, but if it is to be used with the interface described here the polarity of the signal after the output gate must be inverted. Transistor T2 on the interface board is used for this, as shown in figure 2b. The track between PB0 (pin 25 of U2) and pin 9 of U26 on the KIM board must be broken, after which T2 can be wired in series as shown. The signal at output A-U on the application connector now has the correct polarity to drive the current source (T3 on the interface board).

The printed circuit board

All the options described, both for
Table 1

MEMORY-DUMP ROUTINE BY D. HENDRIKSEN

```
0C00 C4 BC 35 C4 00 31 C4 BC 37 C4 86 33 C4 BC 36 C4
0C30 95 32 C4 0D CB FD C4 00 3E BF 80 C4 0A 3E C4 20
0C20 3E 35 01 30 35 40 1C 1C 1C 01 C3 80 3E 35 61
0C30 40 35 40 D4 0F 01 C3 80 3E 31 01 40 31 40 1C 1C
0C40 1C 1C 01 C3 80 3E 01 01 40 31 40 D4 0F 01 C3 80
0C50 3E C4 20 3E C4 10 CB FE C4 20 3E C4 00 1C 1C 1C
0C60 1C 01 C3 80 3E C5 01 D4 0F 01 C3 80 3E CB FB 9C
0C70 E5 BB FD 9C A1 C4 BC CB FF 08 08 08 BB FF 9C FB
0C80 00 98 8F 05 0C 00 30 31 32 33 34 35 36 37 38 39
0C90 41 42 43 44 45 46 01 C4 64 BF 06 06 DC 01 07 C4
0C00 09 C8 20 C4 FB 0F 02 B3 01 98 10 40 D4 01 C8 14
0C00 01 0C 01 06 DC 01 E0 0C 07 00 00 00 00 00 00 00 00
```

Parts list

Resistors:
- R1 = 4k7 (470 Ω)
- R2 = 4k7
- R3 = 4k7*
- R4 = 10 k
- R5 = 1 k
- R6 = 1 k
- R7 = 6k8 or 15 Ω*
- R8 = 270 Ω/1 W

Semiconductors:
- T1, T2 = BC107B, BC547B or eq.
- T3 = BC1778, BC5578 or eq.
- D1 ... D3 = DUS
- D4 = DUS*

* see text.
Where values for SC/MP and KIM differ, the values for the KIM are given in brackets.

SC/MP and KIM systems, can be mounted on the p.c. board shown in figure 3. The component layout for use with the SC/MP system is given in figure 3b; figure 3c corresponds to use in a KIM system.

A so-called modem connector can be used, if required. The mounting holes for the connector correspond to those of the p.c. board, so that the complete unit can then be mounted with only two bolts. The only thing to watch, in this case, is that the components must be mounted as nearly flush with the board as possible - there will not be much room between the board and the panel on which it is mounted! An alternative is to use a right-angle modem connector, so that the board can be mounted horizontally.

Software

The monitor program for the KIM already includes a teletype routine. The selection between a hexadecimal keyboard or teletype input is made by a wire link on the 'application connector'. In this case, since the TTY input is required (even if it is actually used for the Elekterminal), the wire link (or a switch) between pins A-V and A-21 on the connector must be included.

In the Elektor SC/MP system, no provision was made for connecting a teletype. However, only small programs will be required to obtain the necessary functions. As an example, a memory-dump routine is given in table 1. By means of this program, the memory contents will be printed out in hexadecimal - starting at a specified address. The length of the block is determined by the number of lines specified for the print-out. When the complete block has been 'dumped' the processor goes to the 'HALT' mode; operating the HALT-reset key causes a further block to be printed out, etc. The 'modify' routine is used to enter the new start address in memory locations 0C01 (upper address byte) and 0C04 (lower address byte). In the same way, the desired block length can be stored in location 0C13. The program itself is started at 0C00.

The program listing given in table 1 was actually printed using this memory-dump routine, as can be seen from the three underlined data bytes.

The transmission rate is 300 baud.
sweep generator

Determining the frequency response of an amplifier normally requires a series of carefully conducted test measurements, a large supply of graph paper, and plenty of patience. Wrestling with peak-peak values, RMS voltages, dBs, logarithms etc. can prove to be something of a chore, and it is all too easy to make mistakes which 'distort' the final results. However if one possesses an oscilloscope, there is a way of displaying frequency response curves directly upon its screen — provided one also has the instrument described here, namely a sweep generator.

Sweep generators are not usually part of the basic equipment of amateur electronics enthusiasts, for the simple reason that such an instrument is normally too expensive. However if we are content with an instrument which will provide relative results (which is often more important than the measurement of a quantity with absolute accuracy), then there is no reason why a sweep generator should not be included in the test equipment of every hobbyist.

Why sweep?

What exactly is a sweep generator? The simplest way to answer this question is to look at how one would normally set about measuring the frequency response of an amplifier. The usual measurement set-up is illustrated in figure 1. The amplifier under test is provided with an input signal from a low frequency sinewave generator. The amplitude of the amplifier output signal is measured on an AC voltmeter. We now ensure that the amplitude of the input signal is held constant, and measure the amplitude of the output signal for a number of different input frequencies. The results are plotted on graph paper, with frequency along the horizontal axis and amplitude (voltage) along the vertical axis. In this way the frequency response of the amplifier is immediately apparent — how flat it is, at what frequency it starts to roll off, etc.

With this arrangement, each time we wish to make a new measurement the frequency of the sinewave generator must be increased by hand. It would of course be much simpler if, in some way, this could be done automatically. This would also allow a continuous increase of the frequency (instead of in discrete steps), thereby ensuring that we are not jumping over small dips or peaks in the response. Thus what is required is a signal whose frequency increases continuously. In other words, a sweep generator.

Figure 2 illustrates how a sweep generator is used to display the frequency response of an amplifier on an oscilloscope. The sweep generator actually provides two signals: the above described input signal for the amplifier, and a voltage which varies with the frequency of the input signal. The latter signal, designated X, is used to control the horizontal deflection of the oscilloscope (X amplifier). The vertical deflection of the spot is determined by a voltage which is proportional to the amplitude of the amplifier output signal. This is obtained simply by rectifying and smoothing the amplifier output signal. The result of such an arrangement is that the frequency response of the amplifier is displayed directly on the scope screen, with amplitude along the vertical axis, and frequency along the horizontal axis.

Not linear, but logarithmic

As most readers will not doubt know, it is generally the case that a logarithmic scale is used for the frequency axis in such graphs. The question is, how to ensure a logarithmic relationship between the frequency of the sweep generator signal and the external timebase input signal (X). One answer is to increase the frequency of the sweep signal linearly, whilst that of the X signal is increased logarithmically. However a better solution is to let the X voltage increase linearly, and increase the frequency exponentially (with time). In this way there is a logarithmic relationship between frequency and X voltage, whilst the horizontal deflection of the scope will remain constant. This means that the brightness of the trace will also remain constant, and more importantly, affords the possibility of using the (linear) timebase generator of the scope (as not every scope has an X-input).

It should be noted that the vertical axis of the response ought to have a logarithmic scale as well, a facility which is not provided by the circuit described here. Strictly speaking, however, the provision of a logarithmic Y axis is not among the functions of a sweep generator; its job is simply to provide the necessary input signals for the measurement procedure. A suitable circuit (with p.c. board) was published in Elektor, January 1978: the peak programme meter.

Basic circuit

The basic design of the sweep generator is illustrated by the block diagram of figure 3.
An asymmetrical squarewave oscillator is used to trigger a sawtooth generator, which provides the control voltage for the X input of the scope. The X-voltage is also used, via an exponential converter, to control a VCO, resulting in a signal with a frequency exponentially related to the X-voltage. The block diagram is completed by buffers for the various output signals.

The sweep generator has two outputs, the first offers a choice of sinewave or triangle waveforms, whilst the second provides a squarewave. Although triangle and squarewave signals are not generally employed to determine the frequency response of circuits, they are useful in a number of other applications.

The circuit also contains a 'manual' switch, which allows the frequency of the generator to be continuously varied by means of a potentiometer, rather than automatically swept up and down the frequency range.

The circuit in detail

The complete circuit diagram of the sweep generator is shown in figure 4. As can be seen, the circuit contains a number of switches which function as follows:

- S1 - sweep inhibit
- S2 - sweep/manual
- S3 - sinewave/triangle
- S4 - frequency range
- S5 - output attenuator

A more detailed description of these functions will be dealt with later in the text.

An asymmetrical squarewave oscillator is formed by the circuit round T1 and T2. The output of this oscillator is attenuated by R6 and R7 then limited by diodes D1 and D2 which are connected in 'reverse-parallel'. This signal is then used to trigger the sawtooth generator.
consisting of IC1 and the unijunction transistor (UJT) T3. When the voltage on C3 reaches a certain value, T3 turns on, with the result that the voltage at the output of IC1 ramps negative. The period of the sawtooth is approximately 10 seconds, which may appear rather long. However it is important that the frequency of the sawtooth is much lower than that of the lowest VCO signal. After being amplified and inverted by IC2 the sawtooth waveform is used as the external timebase signal for the scope. The peak-peak value of the voltage at point A is 16 V.

The next step is to derive an exponentially related voltage from this sawtooth, and so this end a diode-resistor matrix, consisting of D3...D6 and R14...R21 is used. Basically the matrix forms a voltage divider network in which the size of the input voltage (i.e. A) determines which resistors are included in the divider chain. As with all exponential converters, the diode-resistor matrix provides only an approximation to an exponential signal, however the advantage of this arrangement is that it possesses excellent temperature stability. The output of the matrix is amplified by IC3. The exponential characteristic can be adjusted by means of P4 and P5 – the procedure will be described later in the article. Assuming P4 and P5 are correctly adjusted, a signal which is synchronous with the sawtooth and which increases exponentially with time will...
Oscillator

The actual sweep signal is generated by IC4, a function generator type XR 2206. A detailed description of this IC was contained in Elektor 33 (January 1977).

The input of the IC is protected against excessively large voltages by diodes D7 ... D9 and R31. The IC has two outputs which provide a signal of the same frequency. Depending upon the position of S3, the output at pin 2 (point C) will be a triangle or sine-wave, whilst pin 11 (point D) provides a symmetrical output of opposite polarity. S4, provides five frequency ranges (1-10 Hz, 10-100 Hz, 100-1 kHz, 1-10 kHz and 10-100 kHz). The amplitude of the triangle/sine wave output can be varied by means of potentiometer P7.

With S2 in the 'sweep' position, the oscillator frequency is controlled by the output of the exponential converter. In the manual position, the circuit functions as a conventional function generator, the frequency of which can be adjusted by means of P6.

The sine wave/triangle output is buffered by IC5. This op-amp must be capable of rapidly handling large input signals, therefore a 709 is used, since it has a higher slew rate than the 741 (IC1 ... IC3). The control voltage which determines the amplitude of the sine wave/triangle signal is fed not only to pin 1 of IC4, but also via R35 to the non-inverting input of IC5. This compensates for the effect of the control voltage on the DC component at point C. The buffered sine wave/triangle is fed to a voltage divider, R36 by which the amplitude of the output signal can be varied by 20 dB steps. The circuit is short-circuit proof in all positions of the switch.

The reverse-parallel connected transistors T4 and T5 form a voltage controlled limiter. When the voltage at point E goes high, T4 and T5 receive base current and conduct on negative and positive half cycles of the waveform respectively, so that the sine wave/triangle is limited to the saturation voltage of these transistors. This step ensures that the signal is suppressed during the flyback of the sawtooth. For this reason, the voltage at point E is derived from the sawtooth oscillator which triggers the sawtooth generator.

The XR 2206 also provides a sawtooth output (from pin 11), which is buffered by the circuit round T6 and T7. Although this circuit looks rather unusual, it is basically a discrete equivalent of the totem-pole output of TTL ICs. Because of the effect of D12, when T6 is turned on the voltage at the base of T7 is lower than that at the emitter, i.e. T7 is turned on. The squarewave output is also provided with a switchable attenuator, however, unlike the sine wave/triangle output, there is no suppression of the signal during the flyback of the sawtooth, since there is basically little point in using the squarewave signal in the 'sweep' mode.

Trigger output

In addition to the X-output and the two function output generators, the circuit is also provided with a trigger output, which can be used if the oscilloscope does not have an external timebase input. The signal at the trigger output remains high for the duration of the sweep, and should thus be fed to the sync input of the scope. The trigger output can also be used for the Z-input of scopes which have such a facility, ensuring that the trace is blanked during flyback of the sawtooth.

S1 is a pushbutton switch which, as long as it remains depressed, inhibits the sweep. If the button is pressed during a sweep, the cycle is interrupted and the signal at output 1 is suppressed. S3 switches between sine wave and triangle waveform at output 1. At the same time it also switches the squarewave signal in and out. The squarewave output is only present when S3a is in the triangle position. This prevents pulse spikes being superimposed upon the sine wave output because of crosstalk between the two outputs.

Construction

Care is required in the construction of the sweep generator. Of particular importance is the circuit around IC5, since, in order to obtain a high slew-rate, this op-amp is somewhat undercompensated. This means that it may well exhibit a tendency to oscillate and to counteract this effect R36 has been included. Capacitors C14 and C15 should be montsed as close to the IC as possible.

For potentiometer P6, used to vary the frequency when the generator is used in the manual mode, it may be advantageous to use a multi-turn type with slow motion drive, thus permitting accurate adjustment.

Should the unijunction transistor prove difficult to obtain in certain areas, the following alternatives are offered: 2N492, 2N1671, 2N2418, 2N2420, 2N2422, and a further possibility is the TIS 43. In addition it is also possible to replace the UUT by two separate transistors as shown in figure 5.

The sweep generator requires a power supply which can provide + and -- 15V at 300 mA. A suitable circuit is shown in figure 6 and this can be built on the EPS 9968-5 printed circuit board.

Calibration

The sweep generator has eight preset potentiometers, and before beginning the calibration procedure they should all be set to their mid positions. The same also holds for the control potentiometers of P6 (frequency) and P7 (amplitude). S5 should be set for minimum attenuation, and S2 to 'manual'. With S3 in the 'triangle' position, there should both a triangular waveform at output 1 and a squarewave at output 2. With S2 in its alternative position the squarewave should be absent.

By means of P7 it should be possible to vary the amplitude of the triangle waveform by at least a factor of 10. Should this not be the case, then a smaller value should be chosen for R33. Similarly, with the aid of P6 it should be possible to vary the frequency by a factor of 10. If this is not the case, both R25 and R26 should be reduced.

The symmetry of the triangle and sine waveforms can be adjusted by means of potentiometer P8, whilst the distortion factor of the sine wave can be reduced to a minimum by adjusting P9. For both these procedures an oscilloscope is necessary.

Once the sweep generator has been calibrated, it can be used to drive the sweep generator, generator P1 ... P5 will complete the setting-up procedure. The amplitude of the sawtooth at point A should be adjusted to 16 V peak-peak by means of P1, whilst P2 is used to ensure that the sawtooth is symmetrical about 0 V. Should it prove necessary, the sawtooth can be attenuated by P3 before it is fed to the X-input of the scope.

P4 (amplitude) and P5 (DC voltage level) are adjusted such that the exponential voltage at point B varies between + 2.75 V and + 0.54 V. It will be apparent that P5 also influences P4. Once these two potentiometers have been adjusted the sweep generator is ready for use.

The performance of the circuit — particularly in view of the relatively low cost — is excellent. Within the frequency range of 5 Hz to 100 kHz the amplitude of the sweep signal is constant ± 0.25 dB; below 5 Hz the amplitude increases slightly. The frequency characteristic of the generator is also extremely stable, and the zero voltage setting at output 1 exhibits very little temperature drift.
simple sound effects

We have, somewhere in the Elektor laboratories, a sound effects department, although the exact location has yet to be discovered. There was a widely held opinion that it was found during the last Christmas office party but this was eventually discounted because a) the noises were too lifelike and b) it was not possible to simulate them electronically! We usually associate their normal products with the dying shrieks of tortured cats, horrifying howls and a whole assortment of plops, bangs, whistles etc. However on the odd occasion they do produce sounds suitable for publication and, to prove that this department really does exist, here is their latest circuit design.

The original design for this rather clever sound effects unit was built into a 19inch rack mounting cabinet which unfortunately tended to overheat to an alarming degree (see ‘workshop heater’ in Elektor number 184) and lacked a little on portability. Further research resulted in the following circuit which only uses two CMOS ICs and is very cheap to build. Despite its modest dimensions it will produce a range of sounds from that of an American police siren to one closely resembling the ‘twittering’ of birds.

Sounds simple?
As is apparent from the block diagram of the circuit (figure 1), the basic principle is extremely straightforward. The output of a twelve-bit binary counter is converted into an analogue voltage which is used to control a VCO. As the binary output of the counter increases, the control voltage ramps positive, until the counter resets and the voltage falls to zero, whereupon the count resumes and the control voltage once again starts to ramp positive, and so on. The waveform of the control voltage is thus a periodic sawtooth. The VCO produces the actual output signal of the circuit, whose pitch is determined by the instantaneous amplitude of the sawtooth control voltage. An output buffer amplifier ensures that the signal is sufficiently large to produce an audible tone when fed to a loudspeaker.

The highly individual nature of the resultant sound is due to an unusual feedback configuration. The output signal of the VCO is not only used as the output of the circuit, but as the clock input of the binary counter. Thus the rate at which the counter steps through each count cycle depends upon the pitch of the output signal. In other words, the higher the sound, the faster it varies in pitch. The result is a repetitive beep-beep sound which starts each phrase at a low frequency and rises exponentially to a maximum pitch.

Circuit diagram
The circuit diagram of the sound effects generator is shown in figure 2, and as can be seen, it consists of only a couple of readily-available CMOS ICs and a few assorted resistors and diodes. IC2 forms the 12-bit binary counter. The binary value of the 8 lowest order bits (i.e. those bits which change state most frequently) is converted into an analogue voltage by means of resistors R1...R8. The VCO consists of a simple CMOS oscillator (built around N1 and N2) the RC time constant of which is varied by using transistor T1 and a diode bridge as a voltage-controlled resistor. As the control voltage fed to the base of T1 increases, more current is passed through the diodes, with the result that their dynamic resistance falls. The initial frequency of the oscillator is set with the aid of preset potentiometer P1, which is connected in parallel with the diode network.

The squarewave output of the VCO is fed both to the clock input of IC2 and to an output buffer. The latter is formed by four of the remaining inverters of IC1 connected in parallel.

Construction
A printed circuit board has been provided for the circuit (see figure 3). As can be seen, due to the low component count, the board can be kept very small. The loudspeaker can be any inexpensive 8Ω type capable of handling 500 mA. The supply voltage of the circuit can lie between 4.5 and 10V; at the lowest supply voltage the current consumption of the circuit is only 5 mA, which means that a 4.5 V battery could be used, thereby rendering the circuit portable. Note that the volume of the output signal is determined by the supply voltage level: the higher the supply voltage the louder the sound.

The pitch of the output signal can be adjusted by means of P1. Since the pitch directly determines the rate at which the pitch changes, reducing the resistance setting of P1 not only increases the pitch of the output signal but also causes it to increase more quickly. At the minimum resistance settings of P1 the resultant sound somewhat resembles that of a chirping bird.

The value shown for P1 in the diagram (1 MΩ) is chosen to give the maximum adjustment range. However, if desired any value from 10 k to 1 MΩ may be used, with or without fixed series resistors.
simple sound effects

Figure 1. Block diagram of the simple sound effects generator. The output of a binary counter is converted into an analogue voltage which is used to control a VCO. The output of the VCO forms both the output signal of the circuit proper and the clock signal of the counter.

Figure 2. Complete circuit diagram. Two CMOS ICs and a handful of discrete components are all that is required to produce an interesting range of sound effects.

Figure 3. Printed circuit board for the sound effects generator, on which all the components, with the exception of the loudspeaker, can be mounted. The circuit can be battery-powered if so desired (EPS 79077).

Parts list:

Resistors:
R1, R9 = 820 k
R2 = 470 k
R3 = 220 k
R4 = 100 k
R5 = 47 k
R6 = 22 k
R7 = 12 k
R8 = 5k6
P1 = preset potentiometer, 1 M (see text)

Capacitors:
C1 = 120 n
C2 = 100 µ/16 V

Semiconductors:
IC1 = 4049
IC2 = 4040
T1 = BC547B, BC107B or equ.
D1...D4 = DUS

Miscellaneous:
LS = loudspeaker, 8 Ω/500 mW
S1 = pushbutton
It seems safe to assume that the 'BASIC microcomputer' is the cheapest home-construction computer ever described that can be programmed using a higher programming language. The SC/MP is a popular and readily-available microprocessor. Two further good reasons for using it in this microcomputer are that it can readily be incorporated into the Elektor SC/MP system, and that a Tiny BASIC interpreter for this microcomputer is available in ROM (Read Only Memory).

The BASIC computer card described in this article contains three circuits that can be used as more or less independent units. The processor section is a fully buffered end self-contained 'CPU card' with provisions for DMA (Direct Memory Access) and multiprocessing.

The memory section is also fully independent, and contains the BASIC Interpreter (NIBL-ROM) and the address decoder.

Communication with the 'outside world' (the Elektterminal, for instance) is taken care of by the third section: the interface.

To be fully operational, the computer requires at least one 4K RAM card (RAM = Random Access Memory), as described in Elektor, March 1978. The basic BASIC computer therefore consists of not more than two Eurocard-sized printed circuit boards!
similar terminal must be used in conjunction with the BASIC computer.

Programming in BASIC is easily learned, but it is not so easy to explain all the details in a few pages. For this reason, no attempt will be made in this article to explain how to program in NIBL (National's Industrial BASIC Language). The BASIC course, which started in the recent May issue of Elektor, must suffice. It explains BASIC in general and, as required, deals with NIBL in particular. Obviously, it was written with this BASIC microcomputer in mind!

For this article, software is a side issue. The primary concern is the microcomputer hardware.

However, as stated at the outset: if the aim is to program in BASIC, there is no real need to know how the computer works. Most of the following article would therefore appear to be superfluous: certainly if one has some experience in programming in BASIC, the components can simply be mounted on the board and, (after a quick glance at the summary of NIBL statements and commands) everything’s ready to roll.

However, NIBL not only offers the possibility of programming in (Tiny) BASIC; it also provides for immediate addressing of the hardware. For this reason, it can be useful to know a little bit about the actual circuit...

Bird's-eye view of the CPU

The SC/MP (Simple Cost-effective Micro Processor) is an 8-bit µP, with all essential functions integrated on a single chip. As is apparent from the block diagram (figure 1), the SC/MP (type number INS 8060) contains four 16-bit registers: the program counter and three pointer registers. These 'pointers' play an important part in the (auto-) indexed addressing of the memory and input/output units.

The (8-bit) extension register is of particular interest, since it offers a serial input/output facility with a minimum of fuss. The cassette interface in the Elektor SC/MP system makes full use of this possibility. A UART (Universal Asynchronous Receiver/Transmitter), as used in the Elekterminal, can also be made redundant by utilising the SIN and SOUT connections.

The status register can also be used for serial transfer of data. The three 'flag' connections can be used as outputs: 'sense A' and 'sense B' are both serial inputs. In fact, NIBL uses Flag 0 and Sense B as serial data out- and input respectively.

The INS 8060 can address 64k bytes of memory. This requires 16 address lines, 12 of which are brought out direct via pins of the IC. The four remaining MSB's (Most Significant Bits) are applied to four lines on the databus during the NADS (Negative Address Data Strobe, on pin 39). If these four bits are left unused, the SC/MP can address only 4096 bytes of memory. This 4K memory is called a 'page'; the four MSB's can therefore be used to address 16 pages of memory. The SC/MP will not, of its own accord, 'turn to a new page'. This requires an explicit instruction in the program. When programming in BASIC, nothing could be simpler: for example, the 'statement' PAGE = PAGE + 1 causes the µP to proceed to the next page.

DMA and multiplexing

The SC/MP has an extremely useful facility, absent in many other µPs: all the outputs used for writing into memory etc. employ so-called Tristate logic. This means that they can not only be made 'hard' logic 1 or 0; a third state is also possible, where the outputs are 'floating' with a high output impedance. In this third state, the processor no longer has any effect on the address and databus: as far as any other units are concerned it is no longer 'online' Another microprocessor can then take over (multiplexing), or a terminal can be used for immediate access to the memory. The latter option is normally referred to as DMA, for Direct Memory Access. It is not really the intention that the (human) operator should proceed to 'walk around inside the memory'; the main advantage of DMA is that it can save a considerable amount of (computer-) time when transferring large blocks of data from the memory to peripherals - floppy disc, for instance.

Instruction set

The SC/MP recognises 46 instructions, divided into nine groups; these instructions can be used in up to five different addressing modes. A detailed description of the complete instruction set, with all its variation capabilities, is way outside the scope of this article. I would require pages and pages (both magazine and human memory) and, moreover, it would be rather pointless. After all, this computer can be programmed in BASIC!

Detailed information is provided by the manufacturer, in the documentation listed at the end of this article. This not only explains the instruction set, but also contains full details on how to program in machine language and provides detailed technical information.

Block diagram

The BASIC card consists of three relatively independent sections. In fact, it doesn't really do justice to this design to call it a 'BASIC card', since its use are by no means limited to a mere BASIC
computer. Right from the start, the intention was to produce a design with a minimum component count and maximum flexibility for different applications. The final result is all that we had hoped for.

The BASIC card is virtually a complete microcomputer: only the program memory must be added. The minimum memory requirement is 2048 bytes (sufficient for approximately sixty program lines), or half a 4K RAM card (ECS 9885). Obviously, any other 'memory' with the same capacity (or more) will do instead.

As illustrated in the block diagram (figure 2), the p.c. board contains three distinct sections. The most important of these is the processor section, consisting of the CPU and associated buffer circuits for the address bus, data bus and the main control signals. These buffer circuits make it possible for the CPU to work with extensive memory and peripheral systems. In short, this section is the ideal heart of a larger system.

A small but useful extension of the processor circuit is the RS232C/V24 interface. This section is connected to the processor's flag output and sense B input, which are used as serial output and input both in NIBL and in various other applications. For instance, this interface opens the possibility of connecting the unit direct to a terminal or teletype.

The processor can itself take care of the necessary conversion from parallel to serial data format and vice versa— if the necessary software is available, that is. The saving in cost of hardware is well worth the additional processor-time required for this conversion.

The third and last section on the BASIC card is the Read-Only Memory. The complete NIBL-BASIC interpreter is supplied in a single so-called maxi- ROM. With its 32 Kbit (4096 bytes) memory capacity, this IC represents the absolute limit in Large Scale Integration (LSI) until quite recently, when a ROM with a 64 Kbit storage capacity was announced... It is to be expected that we will see ever larger ROMs appearing for some time to come.

The inputs to the ROM represent a negligible load on the address bus, so there is no need to add buffer stages at this point. The ROM outputs, however, have a very low drive capability; for this reason, an output buffer is required.

The advantage of the system outlined above is that the processor and ROM sections are fully independent units. Although both are mounted on the same p.c. board, their only means of communication is via the general system bus— the same bus that is used for communication with any other part of the system. This means that it is possible, for instance, to fully utilize the processor's capabilities in a particular application where the ROM is not required.

The circuits

The circuits of the processor section and the associated RS232C/V24 interface are given in figure 3.
The interface does two jobs. In the first place, the TTL logic level at the flag \( \Phi \) output of the processor must be converted to RS232C/V24 level. This means that logic 1 must be at least +5V and not more than +15V; similarly, logic \( \Phi \) must be some level between -5V and -15V. As in the Elekterminal, the logic levels chosen in this circuit are +5V for logic 1 and -12V for logic \( \Phi \) — for the simple reason that these levels correspond to common supply voltages. The fact that they are asymmetrical with respect to 0V has no effect on the realizability of data transfer.

The flag \( \Phi \) output of the processor drives transistor T1; in turn, this transistor switches a current source (consisting of T3 and a few resistors and diodes). The advantage of using a current source at the output is that it is short-circuit proof. Furthermore, it then becomes relatively easy to obtain a low output impedance, as required by the RS232C/V24 standard. Should a standard TTL level output be required for some application, it is sufficient to add one extra diode (D4). Logic \( \Phi \) will then correspond to -0.6V (and logic 1 remains +5V); the interface circuit is then a short-circuit proof TTL output buffer. The second thing the interface must do is limit the logic levels at the sense B input of the processor. This is easily accomplished by T2 and D3; R14 limits the input current to a comfortable level.

The basic principles of the processor section have already been explained. However, some further explanation of the circuit is called for — particularly where the Direct Memory Access and multiprocessing facilities are concerned. The CPU, or Central Processor Unit, (IC1) receives clock pulses from an internal oscillator, with an external crystal to determine the frequency. From this clock signal, the NRDS (Negative Read Data Strobe) and NWDS (Negative Write Data Strobe) are derived.

The address and data outputs of the CPU have a limited drive capability. For this reason, the address bus is buffered by IC2 and IC3; similarly, IC4 and IC5 are included as databus buffer. These four ICs have an interesting feature: the input circuits incorporate PNP transistors in such a way that the input current is limited to 100 \( \mu \)A.

A shift register (IC6) is used as a buffer for the four highest address bits (MSBs). Using the 74LS95 at this point has the advantage that the NADS (Negative Address Strobe) can be used, without need for an inverter, to read in the four MSBs to the register.

The NADS is also used to control the databus buffers, in conjunction with the NRDS and NENOUT signals (Negative Read Data Strobe and Negative ENABLE OUTput, respectively). This combination may seem rather strange to those of our readers who have previously studied the Elektron SC/MP system. One would expect that the NWDS (Negative Write Data Strobe) would also be involved in the control of the databus buffers. After all, the NWDS is supposed to control...
Means of the link shown as a dotted line in Figure 3) it will also be at logic 0 level. With both necessary conditions now fulfilled, the SC/MP will proceed to fetch its first instruction.

This first 'read' cycle is illustrated in Figure 5. Shortly after the NBREQ output goes to logic 0, the NADS signal appears. The shift register (IC6 in Figure 3) takes this as its cue to store the four MSBs of the address; simultaneously flip-flop NS/N6 is set, switching the databus buffers into the write mode. However, when the NRDS signal appears it will reset this flip-flop and switch the databus buffers into the 'read' mode. The read cycle is terminated by a brief pulse on the NENOUT connection. In this case, the NENOUT pulse has no effect on the buffers—they had already been switched back to the floating state at the end of the NRDS pulse, as shown in Figure 5.

The sequence of operations during the write cycle is similar, with one major difference: the output of N6 holds the databus buffers in the write mode for a much longer period. In fact, the NWDS signal falls well inside this period. The result is that the data to be stored are present at the memory input well before the NWDS signal appears, and remain there for a short time after this pulse is terminated. Finally, the NENOUT pulse causes the buffers to revert to the floating state.

The advantage of the system outlined above will become apparent from a closer look at the multiprocessor facilities that the SC/MP has to offer. Figure 6a gives a rough outline of a microcomputer system in which several SC/MPs are used. The first of these is connected in the same way as in the single-processor system described so far. For all the following SC/MPs, however, there is a minor modification to the circuit: the NENIN input of each is connected to the NENOUT of its predecessor in the
chain.

After the initial reset, the situation for the first processor is exactly as outlined above. All other processors, however, must wait for their turn: as long as one CPU is using the bus, all others must keep off. The principle is clear from figure 4: each time a CPU wants to 'get on the bus', it will first check the logic level on its NBREQ input. A logic 0 at this point signifies that one of the other SC/MPs is performing a read or write cycle at that moment, so that the bus is busy.

The interplay between the various CPUs is further determined by the NENIN and NENOUT signals. The rules of play are as follows. When a processor is using the system bus, its NENOUT is always at logic 1; if it is not on the bus, its NENOUT assumes the same logic level as that present at its NENIN. Bearing in mind that the NENIN must be at logic 0 before the actual read or write cycle can be initiated, the sequence of events is as follows.

Assume that a CPU somewhere in the middle of the chain wants to store some data in memory. Testing the NBREQ line, it discovers that this is at logic 0 and so it is forced to sit back and wait its turn. As soon as the NBREQ line goes high, the CPU quickly jumps in and pulls this line low again, claiming its share. This pulls the NENIN of the first SC/MP low and, assuming that this CPU is not interested in the busses, its NENOUT will follow — passing the logic 0 level on to number 2. The low NENOUT/NENIN level is passed down the chain in this way until it reaches the CPU that requested entry to the bus. This unit takes this signal as a sign of approval, maintains its own NENOUT connection at a logic 1 level and proceeds to store the data.

It is, of course, conceivable that two CPUs jump in simultaneously when one other goes off the line — both pulling the NBREQ line down to logic 0. No problem. The low level on the NENOUT/NENIN connections is passed down the chain until the first of the two CPUs is reached — and stops here! Only when that unit is finished with its read or write cycle will it produce a logic 0 level at its NENOUT (the NBREQ remains low because the second CPU is still holding it down), this signal then goes further down the chain until the second CPU is reached, and only then can it get onto the busses.

The same principles are involved in a Direct Memory Access (DMA) system: any other units (a terminal, for instance) that require direct access to the busses must include logic gating that provides the same relationships between 'NBREQ', 'NENIN' and 'NENOUT' signals. They can then be linked into the chain in exactly the same way.

Memory

As stated earlier, the complete BASIC interpreter is stored in a single IC. This makes the memory circuit in the NIBL computer simplicity itself (figure 7). One integrated circuit, 74LS155 (IC9), is used as address decoder. It detects the four MSBs of the address and it is wired in such a way that the NIBL-ROM (IC10) is located on page 0 in the memory. The remaining twelve address lines go direct to the ROM; the outputs from the memory are buffered (IC11) and applied to the databus.

The output from the address decoder is also brought out to pin 30c of the edge connector. In the Elektor SC/MP system, this line is used for control of the databus buffer (EPS 9972). With this extra connection, the BASIC microcomputer is suitable for use as a replacement for the original CPU card in an existing Elektor SC/MP system with or without databus buffering.
NIBL

The NIBL-BASIC interpreter is a 4096-byte program for the SC/MP, that is used to 'translate' BASIC statements and commands to routines in machine language.

Use of BASIC as a programming language is explained in the BASIC course that is included as a series of supplements in the Elektor issues from March this year on. A brief summary of the commands and statements that are available when using NIBL is included in this article; some other details also need further clarification.

NIBL (National's Industrial BASIC Language) expects to find RAM storage area from address 1000h on (the 'H' stands for hexadecimal). The first 285 bytes of this memory are used by NIBL for storing data. All remaining memory from there on (i.e. from address 111Eh) is available to the user.

Once the reset key has been operated, NIBL is ready to receive program lines. Single statements can be entered without output a program line number, if required: in that case they will be carried out immediately (so-called 'direct' or 'immediate' mode). This can be particularly useful when testing a (section of) program. In the direct mode, variables can be given certain values so that the program can be started from a well-defined initial situation.

A program can be entered in two ways: from the keyboard of a terminal, or by means of a paper-tape reader or some similar device. In the latter case, the reader-relay should be controlled by the flag 1. Output, however, relatively few people have access to a paper-tape reader and the so-called 'hole-puncher', so a tape or cassette recorder will normally be used instead. For this, a cassette interface is required, as well as some additional 'software'.

The NIBL statements and commands are based on Tiny BASIC. However, NIBL contains several additional features. The most important of these are the DO...UNTIL routine, which is derived from PASCAL, and the 'Indirect Operator'. The latter replaces the PEEK and POKE statements in other BASIC dialects; it can be used for direct addressing of the memory and I/O (Input/Output devices). Of lesser importance — although it can be useful — is the possibility of using so-called 'text variables'.

NIBL statements and commands

Program entry (program lines)

- a line without a line number is carried out immediately.
- a line with a line number is inserted in the program in the correct (numerical) position.
- line numbers from 0 to 32767 = 2^{15} - 1) can be used.
- spaces are not permitted within 'Key words' (LET, IF, THEN, GOTO, GO-SUB, GO, TO, SUB, RETURN, IN-
- PUT, PRINT, LIST, CLEAR and RUN).
- otherwise, spaces can be added in the program text as desired.
- SHIFT/O (or back-arrow on a tele-
- type) deletes the letter that was typed in last.
- CONTROL/H (or backspace on a video terminal) has the same effect as SHIFT/O.
- CONTROL/U deletes the line that is being typed in at that moment, without affecting the data stored under that line number in memory.

Program control (commands)

- CLEAR returns all variables and 'stacks' to their initial state (usually zero).
- NEW erases page 1 in the memory.
- NEW n (where 2 < n < 7) erases the corresponding page in memory.
- LIST initiates a print-out of the program from the first line or of the line number specified (e.g. LIST 290).
- RUN starts the program (starting at the first line).
- GOTO n (where 0 < n < 32767) starts the program at the line number specified, without resetting the variables and stacks.

Variables, constants, operators

- 26 variables can be used: the letters A to Z.
- all operations ('expressions') are carried out using 16-bit 'two's complement' numbers.
- arithmetic operators: +,-,*,/.
- comparison symbols: <=,=,=,=,<,>=.
- logic operators: AND, OR, NOT.
- decimal constants must remain within the range from −32767 to +32767.
- hexadecimal constants are recognised as such when preceded by the symbol #. Not more than four digits (16 bits) are permitted.
- program lines may contain more than one statement, provided the statements are separated by a colon (:).

Functions

- RND (a, b) generates a random number within the range from a to b.
- MOD (a, b) gives the remainder after the division a/b.
- STAT calls up the contents of the status register in the SC/MP.
- PAGE calls up the number of the page in memory that is currently in use.
- TOP calls up the upper boundary of the NIBL program, as a decimal address.

INPUT/OUTPUT statements

- INPUT X
- INPUT X, Y, Z
- PRINT "THIS IS NIBL"
- PRINT "F = \text{M} * A"
- PRINT "SKIP", X, "PAGES";

Note that the semicolon (;) suppresses the automatic CR/LF (Carriage Return/Line Feed) after a print statement.
Assignment statements
- LET X = 7
- E = 1 * R
- STAT = #70
- PAGE = PAGE + 1
- LET @ A = 255
- @ (T + 36) = #FF
- B = @ (TOP + 5)

Control statements
- GO TO 15 or GOTO 15
- GOTO X + 5
- GO SUB 100 or GOSUB 100
- RETURN
- IF X + Y > #1A GOTO 15
- IF A = B LET A = B-C
- FOR I = 10 TO 9 STEP -2
- NEXT I
- FOR K = 1 TO 5
- DO. X = X + 1: UNTIL (X = 10) OR (@X = 13)

Indirect operator
- the @ symbol can be used for immediate addressing of a location in memory; for instance: V = #2000: LET @ V = 100 results in the decimal number 100 being stored at memory location 2000h. Similarly, LET W = @ V gives the variable W the value stored in memory location V.

String handling (text facilities)
- $A = "ONE LINE OF TEXT"
- PRINT $T, $ (TOP + 72)
- INPUT $U (U + 30)
- U = $ (TOP + 2 * 36)

Sandries
- LINK (address): The program is continued in machine language, from the address indicated. The address must be given as a decimal number.
- REM offers the possibility of adding explanatory text (comments, reminders) to the program.
- END: this statement is used to conclude a program, and to add ‘break points’.

Error indications
As soon as a program is started, error indications may appear as a result of incorrect or incomplete use of NIBL. The general error indication format is as follows:
... ERROR AT ...

The first four characters indicate the type of error; the final two characters give the line number. For example, incorrect use of a statement at line number 4500 would result in the print-out:
SMT ERROR AT 4500

Error indications in NIBL all use ‘words’ of up to four letters. The following indications are possible:
AREA The memory space available on the chosen page is exceeded.
CHAR Redundant or incorrect characters in or following a statement.
DIV0 Division by zero.
END No quotation marks after text to be printed.
FOR FOR is not followed by NEXT;
NEST Subroutine possibilities are exceeded.
NEXT NEXT used without FOR.
NOGO The line number specified in a GOTO or GOSUB statement does not exist.
RTRN RETURN was not preceded by GOSUB.
SNTX Incorrect syntax.
STMX Incorrect use of a statement.
UNTIL UNTIL is used without DO.
VALU Incorrect constant or number outside the range.

The p.c. board
The complete circuit can be mounted on the p.c. board shown in figure 8. The board size corresponds to that used in the Elektor SC/MP system: it is Eurocard format, and the edge connector corresponds to the system bus. A second connector is included on the other end of the board; this is intended for connecting a teletype or videoterminal according to the RS232C/V24 standard. This 25-pin connector is variously referred to as a ‘female modem connector’ and as a ‘D connector’.

Where possible, the component layout shown in figure 9 indicates which wire links should be included for a particular application. Reference to figure 3 should further clarify matters.

A complete microcomputer
The unit described here obviously requires a few additional circuits to be fully operational. A minimum system would consist of one bus board, a power supply board, one 4K RAM card and the BASIC computer card described in this article. The system can be extended by adding up to six memory cards. An obvious choice for input and output unit is the Videoterminal. The complete Elektor BASIC microcomputer would then consist of the units shown in figure 10.

Lit.
1. SC/MP data sheet, pub. no. 42030522-2/001A
2. SC/MP instruction guide, pub. no. 4200110A
3. SC/MP technical description, pub. no. 4200079A
4. SC/MP microprocessor applications handbook, pub. no. 42030523/001A
5. SC/MP programming and assembler manual, pub. no. 4200094B
A BASIC interpreter for the Elektor SC/MP system

A BASIC interpreter for the SC/MP has been available for some time. However, this can only be used in systems where page 0 is available for storing the interpreter program. In the Elektor SC/MP system, part of page 0 is used for the monitor program. Even so, an adapted version of the interpreter CAN be incorporated into the Elektor system — as described in this article.

(D. Hendriksen)

The BASIC interpreter for the SC/MP is known as NIBL. This is an abbreviation of National's Industrial BASIC Language.

This interpreter program occupies nearly 4K bytes, or one page in a SC/MP system. It would be asking too much to expect a complete BASIC interpreter in this area; for this reason, NIBL is derived from Tiny BASIC. Consequently, only whole numbers can be used in calculations, and the number range is limited: only numbers between –32767 and +32767 are permitted. Furthermore, 'scientific' calculations are outside the scope of NIBL; fortunately, they are not really essential.

Looking on the positive side, NIBL has some capabilities that are not included in Tiny BASIC. In fact, NIBL is more powerful in some ways than more sophisticated BASIC dialects. This is especially true of the IF...THEN...statement and the DO...UNTIL loop. NIBL is intended for self-contained SC/MP systems, where the interpreter can be started by operating the 'reset' key.

The programs can be stored in pages 1...7. As mentioned above, page 0 is normally occupied by the NIBL interpreter itself. Part of page 1 is used as 'scratch-pad memory' by the interpreter, so some RAM must be reserved in this area.

After starting the interpreter program (by means of the 'reset' key), NIBL will first check to see whether a program is present in page 2. If so, it will run this program immediately; if not, it will prepare page 1 to receive a program and wait until this is entered. If a different page is to be used, this can be specified by using the PAGE=n (n command, where n is 1...7.

Fitting NIBL into the Elektor SC/MP system

If NIBL is to be used in the Elektor system, some modifications are required. Page 0 is not available for the interpreter, since this area is used in part by 'Elbug'. Something's got to move, and in this case it's the interpreter.

Fortunately, the SC/MP's CPU structure makes it a relatively easy matter to move a program. Normally, only instructions relating to pointer manipulations need changing. There are, of course, exceptions to this rule... and NIBL is one of them. It not only uses the three pointers: in the course of the program, some data-bits are also used to determine addresses. As a result of all this, the NIBL version described here contains some 300 modifications with respect to the original.

Placing Elbug on page 0 offers both advantages and disadvantages. The main disadvantage is that NIBL has to be moved; the main advantage is that the cassette routines in the monitor program can be used for storing programs on tape. In the Elektor version, there is no need for a paper-tape reader/puncher, in the original version of NIBL, some further modifications would be required to obtain the same easy cassette storage facility.

Modifications

It was decided to move the interpreter program to page 1. Admittedly, this costs one page of program memory — leaving six pages for the user. The possibility was considered of moving the interpreter out past the program memory — 'above' page 7 — but this would require a large number of additional modifications.

When the interpreter is moved, its 'scratch-pad memory' will also move up one page, to page 2. Therefore, RAM must be available at the top of this page. The interpreter program itself can be stored in EPROM. This is cheaper than using a complete 4K RAM card and, furthermore, the interpreter is then always available for immediate use. The RAM area at the top of page 2 must consist of at least 2K bytes. This is sufficient for a BASIC program of approximately 60 lines — more than enough for the first experimental programs.

Since the interpreter is on page 1,
Elbug must be used to start the program. The normal hex-I/O start procedure is used; since the desired program is on page 1, the initial command is "ru1000m".

Once started in this way, the first thing the interpreter does is look for a program on page 3 (not page 2; everything has been moved up one page!). If it finds a program (herein called ROM), this will be run immediately. This first program can, if necessary, run over more than one page. However, as when programming in machine language, a pointer change will then be required; when programming in NIBL, this is achieved by entering the instruction PAGE = PAGE + 1. The interpreter will 'read' this as an instruction to continue the program on the first line of the next page.

Obviously, this is a useful feature—not only when running an initial program that is stored in ROMs, but also when programs are stored in RAM. To achieve this latter capability, some further modifications in the original NIBL interpreter program proved necessary.

The problem is that the original NIBL version not only looks for a program in page 2; it also requires that this program is stored in ROM. If the program is stored in RAM, the interpreter refuses to run it! Not only that, it also blocks running programs stored on any of the other pages at the same time.

The reason for this 'mushiness' is that NIBL, on finding a program on page 2, proceeds to write an 'end-of-program' indication at the top of each page—or tries to, at least. This indication consists of 'Carriage Return' (BD), followed by
If the program on page 2 was stored in ROM, no harm is done: the contents of the memory location at the top of the page cannot be altered, so the 'end-of-program' indication is not stored there. A jump to the next page for the continuation of the program is also possible, provided this continuation is also stored in ROM.

In the Elektor SC/MP system, however, programs will normally be stored in 4K RAM cards. The 'end-of-program' indication would then block every page. For this reason, NIBEL-1 is modified to...

**Table 1. Listing of the 4K NIBEL-1 interpreter.**

<table>
<thead>
<tr>
<th>Address</th>
<th>Bead rate</th>
</tr>
</thead>
<tbody>
<tr>
<td>0155</td>
<td>100</td>
</tr>
<tr>
<td>0157</td>
<td>200</td>
</tr>
<tr>
<td>0188</td>
<td>300</td>
</tr>
<tr>
<td>0190</td>
<td>400</td>
</tr>
<tr>
<td>0192</td>
<td>500</td>
</tr>
<tr>
<td>0194</td>
<td>600</td>
</tr>
<tr>
<td>0196</td>
<td>700</td>
</tr>
<tr>
<td>0198</td>
<td>800</td>
</tr>
<tr>
<td>019A</td>
<td>900</td>
</tr>
<tr>
<td>019C</td>
<td>1000</td>
</tr>
</tbody>
</table>

*Jeffrey A. Pfeiffer, 'NIBEL-1', Elektor Electronics, May 1979 - Page 5-49*
ensure that this indication is only stored at the top of all pages under condition that no initial program is found on page 3. The only page that will still be blocked, initially, is page 2. This is no problem, though: pages 3...7 provide more than enough memory space for any initial program.

Having entered and tested BASIC programs, the cassette routine in Elbug can be used for storing them on tape. When retrieving, they are, however, a minor problem remains to be resolved: unless a program is stored on page 3, any programs entered on the other pages will immediately be blocked by the interpreter, as described above. One further modification in the interpreter and a slightly more extensive 'start' procedure are required to cure this.

The complete program

Although the main points have already been discussed, it is perhaps a good idea to give a brief survey of the complete system.

The starting point is a complete Elektor SC/MP system, including Elbug and the associated cassette interface. The NIBL-E interpreter is located on page 1—it can be stored in either ROM or RAM.

A listing of this program is given in table 1. Page 2 must contain at least 2K of RAM, as scratch-pad memory for the interpreter; a small program can also be stored here. Extending page 2 to 4K of RAM provides space for more extensive programs.

Either ROM or RAM storage area can be included on the remaining pages (3...7), as required.

To be able to communicate with the interpreter (by means of a terminal, for instance), a small interface circuit must be included. This adapts the TTL logic levels in the SC/MP system to RS232C or V24, and vice versa; it also ensures correct polarity of the various signals. The in- and outputs from the interface can be hard-wired to the terminal, or a (standard) connector can be mounted on the p.c. board. The interface circuit and p.c.b. are described elsewhere in this issue. A suitable terminal is the 'Elketerm'; this can be connected to a normal TV set via the UHF/VHF modulator.

Transmission speed

In the original version, communication with the interpreter runs at a rate of 110 baud. The same is true of the NIBL-E version given in table 1. However, if it is used in conjunction with the Elektermel, a much higher transmission rate is possible: up to 1200 baud.

Obviously, the software will have to be adapted if the transmission rate is changed. The memory locations that are affected by the transmission rate are listed in table 2; the data for the four most common transmission rates are also included in this table. The values given are valid both for a SC/MP system with 1 MHz crystal and for a SC/MP II system with a 2 MHz crystal.

The NIBL interpreter opens the possibility of connecting a paper-tape reader to Sn. The reader-relay is controlled by the 'flag 1' output of the processor, via an output buffer. When developing NIBL-E, however, it was assumed that this facility would not be required, since the Elbug cassette routines will normally be used instead. However, it is a relatively simple matter to provide a 'paper-tape' input: the data in two addresses must be changed (1F7D becomes 92 and 1F8F becomes FD), and the reader is connected to the sense B input (via a parallel-to-series converter).

Storing a program on paper-tape is a simple matter: a LIST command provides simultaneous outputs to the terminal and to the puncher via flag 9. Normally speaking, the transmission speed for a puncher should not be higher than 300 baud.

Cassette routine

BASIC programs can be stored on tape and played back with the same ease as programs in machine language. The start address for the program on page 2 is 211F (hexadecimal); all other pages simply start at the top of the page, at address 0000 (where P is the page number).

The final address can be found, once the program has been entered, by giving the command PRINT TOP (followed, as always, by Carriage Return). The computer will respond by giving the final address plus one, as a decimal number. In other words, it gives the first address that can be used for a new program. This decimal number (minus one) must be converted to hexadecimal. With both 'begin' and 'end' address known, the Elbug cassette routine can be used to store the program on tape. The jump back to Elbug can be achieved in two ways: either operating the NKB or giving the command LINK 9.

The LINK command is used to call up a program that is stored in machine language; in this case, the Elbug program, starting at address 0000. The LINK command can be followed by an address in either decimal or hexadecimal code. If the hexadecimal code is used, the number must be preceded by the $ symbol.

Having 'dumped' the program on tape, a jump back to NIBL-E is initiated by keying in $ruF80ru. By starting at this address, part of the interpreter's initial procedure is avoided—in particular, the section that might otherwise block all programs. The interpreter now prints a prompt (>), after which the current program can be developed further or a new page can be selected for a new program, using the command NEW (P) (where P is the page number). Note that the lowest page number possible is 2. If an attempt is made to select page 1, the interpreter will simply select page 2 instead.

To load a BASIC program from cassette, the routine is as follows. First, NIBL-E is started with the command $ru0100ru. When the prompt symbol appears, the page that is to be loaded is selected: NEW (P). The next step is to jump back to Elbug: LINK 0. The program can now be loaded in the usual way, using the ca...up instruction; when loading is completed ('Elbug' appearing on the display), the jump back to NIBL-E can be executed ($ru1F80ru). As soon as the prompt symbol is printed, the program can be started by giving the RUN command.

Loading NIBL-E

It is well nigh impossible to load a 4K byte program from the keyboard without introducing errors somewhere along the line. For this reason, it is the intention to include the program on an ESS record in the near future.

Using NIBL-E

Only a few NIBL commands have been mentioned in the course of this article. A more extensive summary is given in the description of the BASIC microcomputer elsewhere in this issue; furthermore, the BASIC course explains the use of virtually all possible NIBL commands.
While on the subject of doorbells (see Random Tune Doorbell, elsewhere in this issue), an alternative gimmick is worth considering.

The circuit of this bell may at first sight appear similar, but there are basic differences between the two designs.

In the Random Tune doorbell circuit, a 'random' succession of tones with 'random' lengths is produced as long as the bell-push is held down. As soon as the button is released, the 'melody' stops.

With the circuit described here, a different effect is obtained. After even briefly pressing the bell-push, a short tone will be played. Holding the button down (or pressing it repeatedly in rapid succession) has two effects: a different melody is obtained, and it lasts longer.

The circuit operates as follows.

By pressing pushbutton switch S1, the inputs of N1 and one of the inputs of N3 are taken low, with the result that pin 7 of IC2 (data input A) is taken high. IC2 is a four-bit static shift register, so that upon each successive clock pulse (provided by the clock generator, N4), this logic '1' is transferred to successive outputs. The clock frequency is approximately 5 Hz. The number of '1's clocked through the shift register will be directly proportional to the length of time that S1 is held down.

Each time that one of the outputs of IC2 goes high, a current is supplied via the corresponding resistor to the base of the current controlled oscillator, Ti. The pitch of the resultant tone is thus dependent upon the state of the various outputs of IC2. At each clock pulse, the '1's in the shift register move up one place, causing a change in pitch; if the pushbutton is depressed at that time, a new '1' will also be entered. One of the outputs (Q4B) is fed back via N2 and N3, so that the '1's in the register will keep going round the loop.

After the pushbutton is released, the circuit will keep running until C1 is discharged (through R1); if the button is pressed repeatedly, the capacitor will remain charged and so the bell will 'run' continuously. The only difference between pressing repeatedly and holding the button down is therefore that a different succession of '1's will be entered, giving a different tune.

With this doorbell, it is necessary to add an output buffer amplifier. Alternatively, the complete CCO (T1, C3... C5 and R9... R12) can be replaced by either the complete output section of the Random Tune doorbell (from P2 on) or by the output section of the Simple Sound Effects generator (from R9 on).

The supply requirements are not critical (5... 15 V, 10 mA); the supply circuit given for the Random Tune doorbell is quite suitable.
8 and 10 bit converters

Two new 8-bit converters, the ZN427 successive approximation A-D converter and the ZN428 latching D-A converter, are available from Ferranti Electronics Limited. The ZN427 is a microprocessor compatible and contains multiplying D-A for instrument applications, successive approximation logic with tri-state outputs for data logging, a 2.5 V precision reference and a comparator. For basic operation, the device requires a minimum of external components, only two resistors and a capacitor.

The ZN428 is also microprocessor compatible and contains multiplying D-A with direct voltage output, latches, and a 2.5 V precision reference. The resolution accuracy is 8 bits ± 0.5 LSB linearity at 25°C whilst the settling time is typically 0.5 microseconds. Both devices are available in moulded or ceramic encapsulations.

A range of 10-bit converters, the ZN432 series successive approximation A-D converter and the ZN433 series tracking A-D converter, has also been announced by Ferranti. The ZN432 is a bipolar monolithic device using ±5 V TTL/CMOS compatible power supplies and containing 10-bit current switching multiplying D-A using a matrix of diffused resistors and requiring no trimming. Successive approximation logic with serial or parallel outputs, and a fast comparator with a good overload recovery. It has claimed that a conversion time of 20 microseconds is guaranteed. The input range can be varied as desired by the selection of an external resistor network.

The ZN433 series IC has many features of the ZN432 together with a window comparator and a 1 μS conversion time for continuous operation making practicable a single channel approach on data acquisition systems. Both the ZN432 and the ZN433 series are presented in 28 pin D.I.L. ceramic packages.

Ferranti Electronics Limited, Fields New Road, Chadderton, Oldham, OL9 8NP, U.K.

Logical analysis test kit

A low-cost analysis test kit (model LTC-1) to meet most design, test, production line, educational and mountain-shooting requirements, has been introduced by Continental Specialities Corporation (UK) Limited. The kit is housed in a portable case and includes a logic probe, digital pulse and logic monitor together with full manuals, application guides, accessory probe tips, adapters and leads.

The logic probe offers a 0.1 Megohm input impedance and can detect pulses as narrow as 50 nanoseconds. Separate switch-selectable TTL/DTL and CMOS/HTL thresholds program the dual threshold window comparator to drive the high and low LED indicators. A built-in pulse stretcher drives the third LED and the pulse-memory switch will latch the pulse L.D. and open the leading edge (positive or negative going) of a single shot at repetition-rate pulse and hold it on until the switch is reset.

The digital pulse provides either single pulses or 100 Hz pulse trains with a push of its button. A pulse indicator LED confirms operation and a TTL/CMOS mode switch selects the proper levels.

The logic monitor slips onto any standard 14 or 16 pin D.I.L. and the state of each pin is indicated by LEDs on the top of the monitor.

Continental Specialities Corporation (UK) Limited, Shire Hill Industrial Estate, Saffron Walden, Essex, U.K.

Single board computer

A powerful microcomputer (the ISBC 86/112 from Intel) has been introduced by GI C Semiconductors Limited. The ISBC 86/12 uses the 5 MHz 8086 16 bit CPU, has up to 8 K bytes of memory, dedicated parallel I/O and a serial communications interface all on the same board. It plugs into the standard Intel MultiBus and can be expanded by using any of the wide range of expansion cards available. These expansion boards include RAMS up to 64 K bytes, ROMS up to 64 K bytes, battery powered RAM boards, PROM programmer boards, mini and standard disc controllers, hard disc controllers, 3M cartridge controllers, cassette controllers, video graphic boards, and a range of analogue I/O boards, keyboard/CRT controller boards, relay output boards, isolated input boards, combination I/O boards, communications controllers etc.

The 8086 CPU is designed to support high level languages and has a comprehensive instruction set which includes multiply and divide in binary, BCD or ASCII. On-board memory includes 32 K bytes of dual-port read/write memory and sockets for up to 16 K bytes of read only memory. The dual-port feature allows both read/write memory to be accessed by both the 8086 CPU and any other bus masters which share the system. The memory can be expanded up to 1 Mbyte while the programmable parallel I/O on the boards extends to 24 lines which can be configured as the application demands. Sockets are available on the board to accommodate standard line drivers and receivers.

GEC Semiconductors Limited, East Lane, Wembley, Middlesex, HA9 7PP, U.K.

Hand-held DMIM

A new high performance hand-held digital multimeter (DMM) has recently been announced by Data Precision Corporation and is available from Farnell International Instruments Limited. Designed the model number 935, it was intended primarily for field use and is a full function 3½ digit DMIM with a basic accuracy of 0.5%. It has a total of 29 measurement ranges, 8 for current (AC or DC), 10 for voltage (AC or DC) and 11 for resistance including both high and low resistance ranges. The push-button switches which select all ranges and functions can be operated with one hand leaving the other completely free for probe use. The high-contrast 0.5 high-liquid-crystal display includes polarity sign, decimal points and a low battery voltage warning indicator.

Farnell International Instruments Ltd.
Sandbrook Wat, Wetherby, West Yorkshire, LS22 4DH, U.K.

Calibration is guaranteed for one year and the unit has full protection from overvoltage, overcurrent and high voltage transients. One thousand volts can be applied to any DC voltage range and 700 V r.m.s. to any AC range. All DC ranges can withstand greater than 5 K volts of 1 microsecond duration. All resistance ranges will tolerate 500 V r.m.s. or DC without damage or loss of accuracy. Current ranges are fuse protected against inadvertent input greater than 2 A standard 9 Volt alkaline battery (PP9 or equivalent) will power the 935 for over 200 hours continuous use. An optional AC mains adapter is available and other accessories extend measurement capability to 1000 A, 40 kV, r.m.f. at 700 MHz or temperature from 60 to +150°C. The 935 is housed in an unbreakable 'Notyl' case and has been designed with the emphasis on field use. Data Precision claim that it can be dropped from bench height without damage or loss of calibration. Its small size, (3½ x 6½ x 1½") and light weight (9 lbs. including battery) makes it a 'very anywhere' personal multimeter.
60 Volt VMOS power FETs

Two new VMOS power FETs have been introduced by Siliconix Ltd. of Swansea, The first of these devices is the VN64GA which has a continuous current rating of 12.5 Amps; applications include use in motor control, high efficiency switching power supplies, switching amplifiers and linear power amplifiers. Packaged in a TO-3 can, the VN64GA features turn-on and turn-off times of 45 nsec, an on-resistance of less than 0.4 ohms and a maximum power dissipation of 1 Watt.

The second device is the high speed VN10KM which features turn-on and turn-off speeds of typically 5 nsec and load currents of up to 0.5 Amp and 1 Amp, respectively. The VN10KM is housed complete with heat sink for maximum power handling (1 Watt at 25°C, in the latest TO-237 (TO-92 plus) package and can be used in applications such as high speed line drivers, TTL and CMOS to high current interfaces, transformer and relay switching and LED digit stobe drivers. VMOS devices require no secondary breakdown in the thermal runaway protection while giving improved reliability. Other advantages include an input drive current of less than 100 mA and high gain and fan-out from standard CMOS inputs.

Siliconix Ltd, Monmouth, Swansway, Sal6 6N9, U.K.

'Soft touch' push button switches

A versatile, multi-pushbutton switch matrix, featuring a very low operating force and the option of having illuminated keys, has been introduced to the U.K. by BIMconsoles Ltd. Produced by Petrick Switches in West Germany, the series 324 is designed primarily for radio, TV and HiFi applications such as channel or function selection, volume control, etc. The switch is available in three standard sizes, having pushbutton matrices of 4 x 2, 6 x 2, or 8 x 2. Each size may be ganged with others to provide multi-pushbutton arrays having 8, 16, 24 or 32 keys. Each pushbutton has a very light action, and requires only the lightest touch to operate fully. This 'soft touch' feature will be of particular interest to designers of light or delicate equipment, where operation of a stiff pushbutton selector switch can cause rocking or tipping.

The normal action is of maintained contact, and a hatching release mechanism ensures that previously operated keys are released at the instant that further keys are pressed. In addition, each matrix may be fitted with a 'muting' switch, which isolates audio circuits when the selector is being operated. This prevents the annoying loudspeaker noise which is often heard during wavechange switching on TV sets and HiFi equipment.

By inserting miniature lamps into the base of each group of pushbuttons, the keys may be illuminated. This is done by 'collecting' light using small plastic prisms, and passing it along the acrylic arms which form the pushbutton supports. In this way, individual keys may be illuminated without the need for separate lamps for each key. Eight and twelve pushbutton arrays require 2 lamps, while a sixteen pushbutton array requires 3 lamps.

Maximum power handling is 1.5 W, with a maximum switching voltage of 30 V DC.

All three basic types in the 324 Series are designed for PCB mounting, and have a regular matrix of contact pins protruding from the back plane.

Imperson Ltd., Imperson House, 23-31 King Street, London W3 9LH.

Display consoles

A range of easy access display consoles with the option of either a satin black aluminium display panel or red, green, or neutral grey, translucent filter windows, for illuminated displays, are now available from Boss Industrial Mouldings Limited. The contoured sides of this BIM7500 series of consoles are of 12.7 mm (0.5") thick, solid oiled walnut, contrasting with the textured sand finished exterior panels. They are available in 9 sizes offering the combination of 6 keyboard panel lights and overall dimensions ranging from 250 x 260 x 112 mm (10" x 10.3" x 4.4") high to 500 x 431 x 200 mm (20" x 17" x 7.9") high with the larger sizes having a fully hinged upper section. The exterior panels of all models are quickly detachable on the removal of 2 or 3 concealed screws. Also available are small desk consoles to accommodate full and half-size keyboards. The BIM7505 and BIM9007 BIMconsoles have removable ABS bottom panels which incorporate stand-off bosses for ease of board mounting. Both sizes are of a piece construction with the 1 mm thick, grey aluminium top panel sitting flush with the upper face of the

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Temperature controlled soldering iron

A range of low voltage soldering irons which are thermally self-limiting at approximately 325°C, 370°C or 410°C and which can be used with many existing soldering stations are available from Teleproduction Tools Limited. Known as the Telpco TL range, these nominal 16-20 Watt irons are available for 12, 24 or 48 Volt operation and are supplied with a detachable high purity iron clad soldering bit which can be interchanged with any of twelve other bits of various shapes and sizes. The iron coating on these bits minimizes the migration of copper molecules from soldering tips thereby increasing bit life and eliminating the time required to redress copper bits. The soldering irons in the TL range feature a fast heat recovery cycle, are light, well-balanced and are manufactured in compliance with CEEI11 and BS3456 regulations.

Fibre-optic lighting system

A compact and portable fibre-optic lighting system for industrial and medical applications which provides complete electrical isolation, variable intensity of cold white light and elimination of overhead glare and shadows has been developed by Valtec Corporation. Known as the series 300, the unit comes complete with a lensing system and 150 Watt light source and is suitable for applications such as microscopic assembly work or examination.

The inspection light is available in a variety of lengths, diameters and fibre-optic bundle combinations to suit requirements. The fibre-optic bundle is inserted into a combination flexible and stay-flat surgical grade interlocking steel (or silicone if desired) gooseneck, with the lensing system and light source at each end.

Valtec Corporation, West Boylston, MA 01583, U.K.
Universal voltage tester

A universal voltage tester has been designed by Verospeed which will detect voltages between 4.5 V and 380 V without switching.

Indication of DC voltage polarity is given by the illumination of a light-emitting diode against positive or negative symbols whilst AC voltages are indicated by the alternate flashing of the LEDs. The probe is well suited for many applications in the telecommunications, automotive, R and D and servicing industries. The tester is fully VDE approved and requires up to 1.5 milliamperes to operate with response time of 3 milliseconds.

Verospeed, Barton Park Industrial Estate, Eastleigh, Hampshire, S05 5RR, England.

(1125 M)

Microwave transistors

Two new microwave transistors, offering high linear power, gain and power-added efficiency, are announced by Hewlett-Packard. Both NPN bipolar transistors, the HXTR-5103 and the HXTR-5104, offer low thermal resistance through the use of a Bed heat conductor in a metal/ceramic package. They also feature T22N gallium resistors for additional ruggedness, and both have dielectric scratch protection over their active areas.

HXTR-5103 has a guaranteed dB compressed gain of 11 dB at 2 GHz, with associated P1dB linear output power of 23 dBm typical at 2 GHz. With excellent uniformity and reliability, this linear power microwave transistor has typical power-added efficiency of 34 percent.

HXTR-5104 provides typical linear output power of 29 dBm at 2 GHz and is useful in amplifier applications ranging up to 4 GHz.

Alphanumeric display modules

A stand-alone dot matrix alphanumeric display system that couples a proven display with a microprocessor-based controller to provide an easy-to-read display with very low power requirements and easy interfacing has recently been introduced by Hewlett-Packard. Incorporated into the microprocessor controller are pre-programmed routines to accept, decode and display standard ASCII data. In addition, the 5.0 volt operation, standard low power schottky TTL compatible inputs and four separate display formatting modes, allow easy interface to keyboard or microprocessor based systems.

The low voltage, compact size, and solid state features are ideal for applications in word processing equipment, desktop calculators, and automatic banking terminals. The HDSS-24XX series provides optional upper and lower case character fonts, or user-programmed custom character sets. Single line 16, 24, 32 or 40 character display lengths are available.

Hewlett-Packard Ltd., King Street Lane, Winnersh, Wokingham, Berkshire, RG11 5AR, England.

(1124 M)

Associated P1dB gain is 9 dB typical at 2 GHz, and power-added efficiency of 35 percent.

Hewlett-Packard Ltd., King Street Lane, Winnersh, Wokingham, Berkshire RG11 5AR, England.

(1126 M)

Digital panel meter

British Physical Laboratories has entered the digital panel meter field with the recent announce-ment of a new cost-cutting range of high quality instruments. BPL heralds the meters as the most competitively priced range offering high accuracy and performance coupled with an extensive series of options. The products will meet the requirements of virtually all users of DPMs.

This new range of digital products is intended to supplement BPL's wide range of moving coil meters. Designed for use in all types of professional instrumentation and measuring equipment, meters can also be supplied to customers' special requirements. Production quantity prices for standard LCD models are under £20 and for LCD models, under £30, with immediate delivery availability. Both LCD (3½ and 4½ digit) and LCD models are built into low profile housings less than one inch (25 mm) high and are also available in stackable casings. The LCD instruments are TTL supply compatible and high-contrast LCD versions are built around the latest CMOS/LSI technology with low power consumption suitable for battery/ portable operation.

Standard facilities include display blanking/dimming, auto zero, sample and hold, overload indication, programmable decimals, display testing and a differential input facility. The meters can be scaled to read in engineering units and autoranging models for both AC and DC are available. Other features offered are non-standard ranges, suppressed zero and BCD outputs. Full stocks of standard Racal-BPL DPMs together with technical back-up are available both from BPL's factory and head office in Radlett and their German office in Neu-Leben. BPL's leading European agents will also be able to supply from stock.

British Physical Laboratories, Marlborough Street, Radlett, Hertfordshire, WD7 7HF, England.

(1130 M)
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